

Linear Algebra (Math 2890) Solution to Final Review Problems

1. Let A be the matrix $\begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$.

(a) Prove that $\det(A - \lambda I) = -(\lambda - 1)^2(\lambda - 4)$.

Solution: Compute $A - \lambda I = \begin{bmatrix} 2 - \lambda & 1 & 1 \\ 1 & 2 - \lambda & 1 \\ 1 & 1 & 2 - \lambda \end{bmatrix}$ and

$$\det(A - \lambda I) = (2 - \lambda)^3 + 1 + 1 - (2 - \lambda) - (2 - \lambda) - (2 - \lambda) = 8 - 12\lambda + 6\lambda^2 - \lambda^3 + 2 - 6 + 3\lambda = -\lambda^3 + 6\lambda^2 - 9\lambda + 4 = (1 - \lambda)^2(4 - \lambda).$$

(b) Find the eigenvalues and a basis of eigenvectors for A .

Solution: Solving $-(\lambda - 1)^2(\lambda - 4) = 0$, we know that the eigenvalues are 1, 1 and 4.

$$\text{When } \lambda = 1, A - (1)I = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$x \in \text{Null}(A - I)$ if $x_1 + x_2 + x_3 = 0$. So $x_1 = -x_2 - x_3$ and

$$x = \begin{bmatrix} -x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}. \text{ Thus } \{u_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, u_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}\} \text{ is a basis of eigenvectors when } \lambda = 1.$$

$$\text{When } \lambda = 4, A - 4I = \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \text{ interchange } \widetilde{r_1} \text{ and } r_2,$$

$$\begin{bmatrix} 1 & -2 & 1 \\ -2 & 1 & 1 \\ 1 & 1 & -2 \end{bmatrix}$$

$$-2r_1 + \widetilde{r_2}, -r_1 + r_3 \begin{bmatrix} 1 & -2 & 1 \\ 0 & -3 & 3 \\ 0 & 3 & -3 \end{bmatrix}$$

$$r_2 + r_3, r_2/(-3) \begin{bmatrix} 1 & -2 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \quad 2r_2 + r_1 \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \quad x \in \text{Null}(A -$$

4I) if $x_1 - x_3 = 0$ and $x_2 - x_3 = 0$. So $x = \begin{bmatrix} x_3 \\ x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$. Thus

$\{u_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}\}$ is an eigenvector when $\lambda = 4$.

(c) Diagonalize the matrix A if possible.

Solution: So $\{u_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, u_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, u_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}\}$ is an basis for R^3 which are eigenvectors corresponding to $\lambda = 1, \lambda = 1$ and $\lambda = 4$. Compute

Finally, we have $A = P \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix} P^{-1}$ where $P = [v_1 \ v_2 \ v_3] = \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$.

(d) Find an expression for A^k .

Solution: $A^k = P \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4^k \end{bmatrix} P^{-1}$ where $P = [v_1 \ v_2 \ v_3] = \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$.

Note that $1^k = 1$.

(e) Find an expression for the matrix exponential e^A .

Solution: $e^A = P \begin{bmatrix} e & 0 & 0 \\ 0 & e & 0 \\ 0 & 0 & e^4 \end{bmatrix} P^{-1}$ where $P = [v_1 \ v_2 \ v_3] = \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$.

Note that $e^1 = e$.

2. Let B be the matrix $\begin{bmatrix} 2 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix}$.

(a) Find the characteristic equation of A.

Solution: $B - \lambda I = \begin{bmatrix} 2 - \lambda & 1 & 1 \\ 0 & 2 - \lambda & 1 \\ 0 & 0 & 1 - \lambda \end{bmatrix}.$

So $\det(B - \lambda I) = (2 - \lambda)^2(1 - \lambda)$. The characteristic equation of A is $(2 - \lambda)^2(1 - \lambda) = 0$.

(b) Find the eigenvalues and a basis of eigenvectors for B.

Solving $(2 - \lambda)^2(1 - \lambda) = 0$, we know that the eigenvalues of B are $\lambda = 2$ and $\lambda = 1$.

When $\lambda = 2$, we have

$$B - \lambda I = \begin{bmatrix} 2 - 2 & 1 & 1 \\ 0 & 2 - 2 & 1 \\ 0 & 0 & 1 - 2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & -1 \end{bmatrix}$$

$$r_2 := r_2 + \widetilde{r_3}, r_1 := r_1 + r_3 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$

The solution of $(B - 2I)x = 0$ is $x_2 = 0$, $x_3 = 0$ and x_1 is free. So

$$\text{Null}(B - 2I) = \left\{ \begin{bmatrix} x_1 \\ 0 \\ 0 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}.$$

The basis for the eigenspace corresponding to eigenvalue 2 is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}.$

When $\lambda = 1$, we have

$$B - \lambda I = \begin{bmatrix} 2 - 1 & 1 & 1 \\ 0 & 2 - 1 & 1 \\ 0 & 0 & 1 - 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$r_1 := \widetilde{r_1} - r_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$

The solution of $(B - I)x = 0$ is $x_1 = 0$ and $x_2 + x_3 = 0$ So $x_1 = 0$,

$$x_2 = -x_3 \text{ and } x_3 \text{ is free. } \text{Null}(B - I) = \left\{ \begin{bmatrix} 0 \\ -x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\}.$$

The basis for the eigenspace corresponding to eigenvalue 1 is $\left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\}$.

So $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ is an eigenvector corresponding to eigenvalue 2 and $\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$ is

an eigenvector corresponding to eigenvalue 1

(c) Diagonalize the matrix B if possible.

From (b), we know that B has only two independent eigenvectors and B is not diagonalizable.

3. Let A be the matrix

$$A = \begin{bmatrix} -4 & -5 & 5 \\ -5 & -4 & -5 \\ 5 & -5 & -4 \end{bmatrix}$$

(a) Prove that $\det(A - \lambda I) = (9 + \lambda)^2(6 - \lambda)$. You may use the fact that $(9 + \lambda)^2(6 - \lambda) = 486 + 27\lambda - 12\lambda^2 - \lambda^3$.

Solution: Compute $A - \lambda I = \begin{bmatrix} -4 - \lambda & -5 & 5 \\ -5 & -4 - \lambda & -5 \\ 5 & -5 & -4 - \lambda \end{bmatrix}$ and

$$\begin{aligned} \det(A - \lambda I) &= (-4 - \lambda)^3 + (-5)(-5)5 + 5(-5)(-5) \\ &\quad - 5(-4 - \lambda)5 - (-5)(-5)(-4 - \lambda) - (-4 - \lambda)(-5)(-5) \\ &= (-4 - \lambda)(16 + 8\lambda + \lambda^2) + 125 + 125 + 100 + 25\lambda + 100 + 25\lambda + 100 + 25\lambda \\ &= -64 - 32\lambda - 4\lambda^2 - 16\lambda - 8\lambda^2 - \lambda^3 + 550 + 75\lambda \\ &= 486 + 27\lambda - 12\lambda^2 - \lambda^3 = (9 + \lambda)^2(6 - \lambda). \end{aligned}$$

(b) Orthogonally diagonalizes the matrix A , giving an orthogonal matrix P and a diagonal matrix D such that $A = PDP^t$.

Solution: Solving $\det(A - \lambda I) = (9 + \lambda)^2(6 - \lambda) = 0$, we know that the eigenvalues are -9, -9 and 6.

When $\lambda = -9$, $A - (-9)I = A + 9I = \begin{bmatrix} -4 + 9 & -5 & 5 \\ -5 & -4 + 9 & -5 \\ 5 & -5 & -4 + 9 \end{bmatrix}$

$$= \begin{bmatrix} 5 & -5 & 5 \\ -5 & 5 & -5 \\ 5 & -5 & 5 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$x \in \text{Null}(A - I)$ if $x_1 - x_2 + x_3 = 0$. So $x_1 = x_2 - x_3$ and

$$x = \begin{bmatrix} x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}. \text{ Thus } \{u_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, u_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}\} \text{ is a basis of eigenvectors when } \lambda = -9.$$

Now we use Gram-Schmidt process to find an orthogonal basis for $\text{Null}(A - (-9)I)$.

$$\text{Let } v_1 = u_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \text{ and } v_2 = u_2 - \frac{u_2 \cdot v_1}{v_1 \cdot v_1} v_1.$$

$$\text{Compute } u_2 \cdot v_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = -1 \text{ and } v_1 \cdot v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = 2.$$

$$\text{So } v_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \left(\frac{-1}{2}\right) \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} + \left(\frac{1}{2}\right) \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix}.$$

$$\text{Now we can replace } v_2 \text{ by } 2v_2 = 2 \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}$$

Hence $\{v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}\}$ is an orthogonal basis of eigenvectors when $\lambda = -9$.

$$\text{When } \lambda = 6, A - 6I = \begin{bmatrix} -4 - 6 & -5 & 5 \\ -5 & -4 - 6 & -5 \\ 5 & -5 & -4 - 6 \end{bmatrix} \sim \begin{bmatrix} -10 & -5 & 5 \\ -5 & -10 & -5 \\ 5 & -5 & -10 \end{bmatrix} \sim$$

$$\begin{bmatrix} -2 & -1 & 1 \\ -1 & -2 & -1 \\ 1 & -1 & -2 \end{bmatrix} \xrightarrow{\text{interchange } r_1 \text{ and } r_3,} \begin{bmatrix} 1 & -1 & -2 \\ -1 & -2 & -1 \\ -2 & -1 & 1 \end{bmatrix}$$

$$\begin{array}{l}
r_2 := \widetilde{r_2 + r_1} \\
r_3 := \widetilde{r_3 + 2r_1}
\end{array}
\begin{bmatrix} 1 & -1 & 2 \\ 0 & -3 & -3 \\ -2 & -1 & 1 \end{bmatrix}
\begin{array}{l}
r_3 := \widetilde{r_3 - r_2}, r_2 := \widetilde{r_2/3} \\
r_1 := \widetilde{r_1 + r_2}
\end{array}
\begin{bmatrix} 1 & -1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}
\begin{bmatrix} x_3 \\ -x_3 \\ x_3 \end{bmatrix}$$

$x \in Null(A-6I)$ if $x_1 - x_3 = 0$ and $x_2 + x_3 = 0$. So $x = \begin{bmatrix} x_3 \\ -x_3 \\ x_3 \end{bmatrix} =$

$x_3 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$. Thus $\{v_3 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\}$ is an eigenvector when $\lambda = 6$.

So $\{v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}, v_3 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\}$ is an orthogonal basis

for R^3 which are eigenvectors corresponding to $\lambda = -9$, $\lambda = -9$ and $\lambda = 6$. Compute $\|v_1\| = \sqrt{2}$, $\|v_2\| = \sqrt{6}$ and $\|v_3\| = \sqrt{3}$.

Thus $\{\frac{v_1}{\|v_1\|} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \frac{v_2}{\|v_2\|} = \begin{bmatrix} -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{6}} \end{bmatrix}, \frac{v_3}{\|v_3\|} = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}\}$ is an or-

thonormal basis for R^3 which are eigenvectors corresponding to $\lambda = -9$, $\lambda = -9$ and $\lambda = 6$.

Finally, we have $A = P \begin{bmatrix} -9 & 0 & 0 \\ 0 & -9 & 0 \\ 0 & 0 & 6 \end{bmatrix} P^T$ where $P = [\frac{v_1}{\|v_1\|} \frac{v_2}{\|v_2\|} \frac{v_3}{\|v_3\|}] =$

$$\begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{bmatrix}.$$

- (c) Write the quadratic form associated with A using variables x_1 , x_2 , and x_3 ?

Solution: Recall that $A = \begin{bmatrix} -4 & -5 & 5 \\ -5 & -4 & -5 \\ 5 & -5 & -4 \end{bmatrix}$ and the quadratic

form in x_1, x_2 and x_3 is $Q_A(x) = x^T Ax = -4x_1^2 - 4x_2^2 - 4x_3^2 - 10x_1x_2 + 10x_1x_3 - 10x_2x_3$. Note that this quadratic is indefinite (b/c it's eigenvalues are $-9, -9, 6$.)

(d) Find an expression for A^k and e^A .

Solution: From $A = P \begin{bmatrix} -9 & 0 & 0 \\ 0 & -9 & 0 \\ 0 & 0 & 6 \end{bmatrix} P^T$ where $P = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{bmatrix}$,

we have

$$A^k = P \begin{bmatrix} (-9)^k & 0 & 0 \\ 0 & (-9)^k & 0 \\ 0 & 0 & 6^k \end{bmatrix} P^T \text{ and } e^A = P \begin{bmatrix} e^{-9} & 0 & 0 \\ 0 & e^{-9} & 0 \\ 0 & 0 & e^6 \end{bmatrix} P^T.$$

(e) What's $A^5\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right)$?

Solution: Recall that $\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$ is an eigenvector of $A = \begin{bmatrix} -4 & -5 & 5 \\ -5 & -4 & -5 \\ 5 & -5 & -4 \end{bmatrix}$

with eigenvalue 6, so we have $A\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) = 6 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$,

$$A^2\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) = A\left(6 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) = 6A\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) = 6^2 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}. \text{ Similarly, we}$$

$$\text{get } A^k\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) = 6^k \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \text{ and } A^5\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) = 6^5 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}.$$

(f) What is $\lim_{n \rightarrow \infty} A^{-n}\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right)$?

Solution: We have $A^{-n}\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) = 6^{-n} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{6^n} \\ -\frac{1}{6^n} \\ \frac{1}{6^n} \end{bmatrix}$. So $\lim_{n \rightarrow \infty} A^{-n}\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) =$

$$\lim_{n \rightarrow \infty} \begin{bmatrix} \frac{1}{6^n} \\ -\frac{1}{6^n} \\ \frac{1}{6^n} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

4. Classify the quadratic forms for the following quadratic forms. Make a change of variable $x = Py$, that transforms the quadratic form into one with no cross term. Also write the new quadratic form.

(a) $9x_1^2 - 8x_1x_2 + 3x_2^2$.

Let $Q(x_1, x_2) = 9x_1^2 - 8x_1x_2 + 3x_2^2 = x^T \begin{bmatrix} 9 & -4 \\ -4 & 3 \end{bmatrix} x$ and $A = \begin{bmatrix} 9 & -4 \\ -4 & 3 \end{bmatrix}$. We want to orthogonally diagonalize A .

Compute $A - \lambda I = \begin{bmatrix} 9 - \lambda & -4 \\ -4 & 3 - \lambda \end{bmatrix}$ and $\det(A - \lambda I) = (9 - \lambda)(3 - \lambda) - 16 = \lambda^2 - 12\lambda + 27 - 16 = \lambda^2 - 12\lambda + 11 = (\lambda - 1)(\lambda - 11)$. So $\lambda = 1$ or $\lambda = 11$. Since the eigenvalues of A are all positive, we know that the quadratic form is positive definite.

Now we diagonalize A .

$\lambda = 1$: $A - 1 \cdot I = \begin{bmatrix} 9 - 1 & -4 \\ -4 & 3 - 1 \end{bmatrix} = \begin{bmatrix} 8 & -4 \\ -4 & 2 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix}$. So

$x \in \text{Null}(A - 1 \cdot I)$ iff $2x_1 - x_2 = 0$. So $x_2 = 2x_1$ and $x = \begin{bmatrix} x_1 \\ 2x_1 \end{bmatrix} =$

$x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$. So $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ is an eigenvector corresponding to eigenvalue $\lambda = 1$.

$\lambda = 11$: $A - 11 \cdot I = \begin{bmatrix} 9 - 11 & -4 \\ -4 & 3 - 11 \end{bmatrix} = \begin{bmatrix} -2 & -4 \\ -4 & -8 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}$.

So $x \in \text{Null}(A - 11 \cdot I)$ iff $x_1 + 2x_2 = 0$. So $x_1 = -2x_2$ and $x = \begin{bmatrix} -2x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \end{bmatrix}$. So $\begin{bmatrix} -2 \\ 1 \end{bmatrix}$ is an eigenvector corresponding to eigenvalue $\lambda = 11$.

Now $\{v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}\}$ is an orthogonal basis. Compute

$\|v_1\| = \sqrt{5}$ and $\|v_2\| = \sqrt{5}$. Thus $\{\frac{v_1}{\|v_1\|} = \begin{bmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{bmatrix}, \frac{v_2}{\|v_2\|} = \begin{bmatrix} \frac{-2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{bmatrix}\}$ is

an orthonormal basis of eigenvectors. So we have $A = P \begin{bmatrix} 1 & 0 \\ 0 & 11 \end{bmatrix} P^T$

where $P = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{-2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}$.

Now $Q(x) = x^T Ax = x^T P \begin{bmatrix} 1 & 0 \\ 0 & 11 \end{bmatrix} P^T x = y^T \begin{bmatrix} 1 & 0 \\ 0 & 11 \end{bmatrix} y = y_1^2 + 11y_2^2$ if $y = P^T x$. So $Py = PP^T x$, $x = Py$ and $P = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{-2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}$.

Note that we have used the fact that $PP^T = I$.

(b) $-5x_1^2 + 4x_1x_2 - 2x_2^2$.

Let $Q(x_1, x_2) = -5x_1^2 + 4x_1x_2 - 2x_2^2 = x^T \begin{bmatrix} -5 & 2 \\ 2 & -2 \end{bmatrix} x$ and $A = \begin{bmatrix} -5 & 2 \\ 2 & -2 \end{bmatrix}$. We want to orthogonally diagonalize A .

Compute $A - \lambda I = \begin{bmatrix} -5 - \lambda & 2 \\ 2 & -2 - \lambda \end{bmatrix}$ and $\det(A - \lambda I) = (-5 - \lambda)(-2 - \lambda) - 4 = \lambda^2 + 7\lambda + 10 - 4 = \lambda^2 + 7\lambda + 6 = (\lambda + 1)(\lambda + 6)$. So $\lambda = -1$ or $\lambda = -6$. Since the eigenvalues of A are all negative, we know that the quadratic form is negative definite.

Now we diagonalize A .

$$\lambda = -1: A - (-1) \cdot I = \begin{bmatrix} -5 - (-1) & 2 \\ 2 & -2 - (-1) \end{bmatrix} = \begin{bmatrix} -4 & 2 \\ 2 & -1 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix}.$$

So $x \in \text{Null}(A - 1 \cdot I)$ iff $2x_1 - x_2 = 0$. So $x_2 = 2x_1$ and $x = \begin{bmatrix} x_1 \\ 2x_1 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$. So $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ is an eigenvector corresponding to eigenvalue $\lambda = -1$.

$$\lambda = -6: A - (-6) \cdot I = \begin{bmatrix} -5 - (-6) & 2 \\ 2 & (-2) - (-6) \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}.$$

So $x \in \text{Null}(A - 11 \cdot I)$ iff $x_1 + 2x_2 = 0$. So $x_1 = -2x_2$ and $x = \begin{bmatrix} -2x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \end{bmatrix}$. So $\begin{bmatrix} -2 \\ 1 \end{bmatrix}$ is an eigenvector corresponding to eigenvalue $\lambda = -6$.

Now $\{v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}\}$ is an orthogonal basis. Compute

$$\|v_1\| = \sqrt{5} \text{ and } \|v_2\| = \sqrt{5}. \text{ Thus } \left\{ \frac{v_1}{\|v_1\|} = \begin{bmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{bmatrix}, \frac{v_2}{\|v_2\|} = \begin{bmatrix} \frac{-2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{bmatrix} \right\} \text{ is}$$

an orthonormal basis of eigenvectors. So we have $A = P \begin{bmatrix} -1 & 0 \\ 0 & -6 \end{bmatrix} P^T$

where $P = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{-2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}$.

Now $Q(x) = x^T A x = x^T P \begin{bmatrix} -1 & 0 \\ 0 & -6 \end{bmatrix} P^T x = y^T \begin{bmatrix} -1 & 0 \\ 0 & -6 \end{bmatrix} y = -y_1^2 - 6y_2^2$ if $y = P^T x$. So $Py = PP^T x$, $x = Py$ and $P = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{-2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}$.

(c) $8x_1^2 + 6x_1x_2$.

Let $Q(x_1, x_2) = 8x_1^2 + 6x_1x_2 = x^T \begin{bmatrix} 8 & 3 \\ 3 & 0 \end{bmatrix} x$ and $A = \begin{bmatrix} 8 & 3 \\ 3 & 0 \end{bmatrix}$. We want to orthogonally diagonalize A .

Compute $A - \lambda I = \begin{bmatrix} 8 - \lambda & 3 \\ 3 & 0 - \lambda \end{bmatrix}$ and $\det(A - \lambda I) = (8 - \lambda) \cdot (-\lambda) - 9 = \lambda^2 - 8\lambda - 9 = (\lambda + 1)(\lambda - 9)$. So $\lambda = -1$ or $\lambda = 9$. Since A has positive and negative eigenvalues, we know that the quadratic form is indefinite.

Now we diagonalize A .

$\lambda = -1$: $A - (-1) \cdot I = \begin{bmatrix} 8 - (-1) & 3 \\ 3 & 0 - (-1) \end{bmatrix} = \begin{bmatrix} 9 & 3 \\ 3 & 1 \end{bmatrix} \sim \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix}$. So $x \in \text{Null}(A - 1 \cdot I)$ iff $3x_1 + x_2 = 0$. So $x_2 = -3x_1$ and $x = \begin{bmatrix} x_1 \\ -3x_1 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ -3 \end{bmatrix}$. So $\begin{bmatrix} 1 \\ -3 \end{bmatrix}$ is an eigenvector corresponding to eigenvalue $\lambda = -1$.

$\lambda = 9$: $A - 9 \cdot I = \begin{bmatrix} 8 - 9 & 3 \\ 3 & 0 - 9 \end{bmatrix} = \begin{bmatrix} -1 & 3 \\ 3 & -9 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 \\ 0 & 0 \end{bmatrix}$. So $x \in \text{Null}(A - 9 \cdot I)$ iff $x_1 - 3x_2 = 0$. So $x_1 = 3x_2$ and $x = \begin{bmatrix} 3x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} 3 \\ 1 \end{bmatrix}$. So $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ is an eigenvector corresponding to eigenvalue $\lambda = 9$.

Now $\{v_1 = \begin{bmatrix} 1 \\ -3 \end{bmatrix}, v_2 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}\}$ is an orthogonal basis. Compute

$\|v_1\| = \sqrt{10}$ and $\|v_2\| = \sqrt{10}$. Thus $\left\{ \frac{v_1}{\|v_1\|} = \begin{bmatrix} \frac{1}{\sqrt{10}} \\ \frac{-3}{\sqrt{10}} \end{bmatrix}, \frac{v_2}{\|v_2\|} = \begin{bmatrix} \frac{3}{\sqrt{10}} \\ \frac{1}{\sqrt{10}} \end{bmatrix} \right\}$

$\left\{ \begin{bmatrix} \frac{3}{\sqrt{10}} \\ \frac{1}{\sqrt{10}} \end{bmatrix} \right\}$ is an orthonormal basis of eigenvectors. So we have $A = P \begin{bmatrix} -1 & 0 \\ 0 & 9 \end{bmatrix} P^T$ where $P = \begin{bmatrix} \frac{1}{\sqrt{10}} & \frac{-3}{\sqrt{10}} \\ \frac{3}{\sqrt{10}} & \frac{1}{\sqrt{10}} \end{bmatrix}$.
 Now $Q(x) = x^T A x = x^T P \begin{bmatrix} -1 & 0 \\ 0 & 9 \end{bmatrix} P^T x = y^T \begin{bmatrix} -1 & 0 \\ 0 & 9 \end{bmatrix} y = -y_1^2 + 9y_2^2$ if $y = P^T x$. So $P y = P P^T x$, $x = P y$ and $P \begin{bmatrix} \frac{1}{\sqrt{10}} & \frac{-3}{\sqrt{10}} \\ \frac{3}{\sqrt{10}} & \frac{1}{\sqrt{10}} \end{bmatrix}$.

5. (a) Find a 3×3 matrix A which is not diagonalizable?

Solution: Let $A = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$. Then $\det(A - \lambda I) = -\lambda^3$ and the eigenvalues of A are zero.

$A - 0 \cdot I = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$. The eigenvector $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ satisfies

$x_2 = 0$ and $x_3 = 0$. The eigenvector is $x = \begin{bmatrix} x_1 \\ 0 \\ 0 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. So there is

only one eigenvector for A and A is not diagonalizable.

(b) Give an example of a 2×2 matrix which is diagonalizable but not orthogonally diagonalizable?

Solution: Let $A = \begin{bmatrix} 1 & 4 \\ 1 & 1 \end{bmatrix}$. Then $\det(A - \lambda I) = \begin{vmatrix} 1 - \lambda & 4 \\ 1 & 1 - \lambda \end{vmatrix} = (1 - \lambda)^2 - 4 = (1 - \lambda)^2 - 2^2 = (1 - \lambda - 2)(1 - \lambda + 2) = (-\lambda - 1)(3 - \lambda)$. So A has two distinct eigenvalues and A is diagonalizable. But A is not symmetric. So A is not orthogonally diagonalizable.

6. Let $A = \begin{bmatrix} 1 & 2 & 2 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \\ -1 & 0 & -1 \end{bmatrix}$.

- (a) Find the condition on $b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$ such that $Ax = b$ is solvable.

Solution:

Consider the augmented matrix $[A \ b] = \left[\begin{array}{ccc|c} 1 & 2 & 2 & b_1 \\ 1 & 1 & 0 & b_2 \\ 0 & 1 & 2 & b_3 \\ -1 & 0 & -1 & b_4 \end{array} \right]$

$$a_2 := \widetilde{a_2 + (-1)a_1} \left[\begin{array}{ccc|c} 1 & 2 & 2 & b_1 \\ 0 & -1 & -2 & b_2 - b_1 \\ 0 & 1 & 2 & b_3 \\ -1 & 0 & -1 & b_4 \end{array} \right]$$

$$a_4 := \widetilde{a_4 + a_1} \left[\begin{array}{ccc|c} 1 & 2 & 2 & b_1 \\ 0 & -1 & -2 & b_2 - b_1 \\ 0 & 1 & 2 & b_3 \\ 0 & 2 & 1 & b_4 + b_1 \end{array} \right]$$

$$a_2 := \widetilde{-a_2} \left[\begin{array}{ccc|c} 1 & 2 & 2 & b_1 \\ 0 & 1 & 2 & -b_2 + b_1 \\ 0 & 1 & 2 & b_3 \\ 0 & 2 & 1 & b_4 + b_1 \end{array} \right]$$

$$a_3 := \widetilde{a_3 - a_2}, a_4 := \widetilde{a_4 - 2a_2} \left[\begin{array}{ccc|c} 1 & 2 & 2 & b_1 \\ 0 & 1 & 2 & -b_2 + b_1 \\ 0 & 0 & 0 & b_3 + b_2 - b_1 \\ 0 & 0 & -3 & b_4 - b_1 + 2b_2 \end{array} \right]$$

$$a_3 \leftrightarrow a_4 \left[\begin{array}{ccc|c} 1 & 2 & 2 & b_1 \\ 0 & 1 & 2 & -b_2 + b_1 \\ 0 & 0 & -3 & b_4 - b_1 + 2b_2 \\ 0 & 0 & 0 & b_3 + b_2 - b_1 \end{array} \right]$$

From here, we can see that $Ax = b$ has a solution if $b_3 + b_2 - b_1 = 0$.

(b) What is the column space of A ?

Solution:

The column space is the subspace spanned by the column vectors. From the computation in (a), we know that the column vectors of

$$A \text{ are independent. So } \text{Col}(A) = \text{span}\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix} \right\}.$$

(c) Describe the subspace $\text{col}(A)^\perp$ and find an basis for $\text{col}(A)^\perp$.

Solution: $\text{col}(A)^\perp = \{x \mid x \cdot y = 0 \text{ for all } y \in \text{col}(A)\}$

$$= \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \mid \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} = 0, \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix} = 0, \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix} = 0 \right\}$$

$$= \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \mid x_1 + x_2 - x_4 = 0, 2x_1 + x_2 + x_3 = 0, 2x_1 + 2x_3 - x_4 = 0 \right\}$$

$$\text{Consider } \begin{bmatrix} 1 & 1 & 0 & -1 \\ 2 & 1 & 1 & 0 \\ 2 & 0 & 2 & -1 \end{bmatrix} \xrightarrow{r_2 := r_2 - 2r_1} \begin{bmatrix} 1 & 1 & 0 & -1 \\ 0 & -1 & 1 & 2 \\ 2 & 0 & 2 & -1 \end{bmatrix}$$

$$\xrightarrow{r_3 := r_3 - 2r_1} \begin{bmatrix} 1 & 1 & 0 & -1 \\ 0 & -1 & 1 & 2 \\ 0 & -2 & 2 & 1 \end{bmatrix} \xrightarrow{r_2 := -r_2} \begin{bmatrix} 1 & 1 & 0 & -1 \\ 0 & 1 & -1 & -2 \\ 0 & -2 & 2 & 1 \end{bmatrix}$$

$$\xrightarrow{r_3 := r_3 + 2r_2} \begin{bmatrix} 1 & 1 & 0 & -1 \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & -3 \end{bmatrix} \xrightarrow{r_1 := r_1 - r_2} \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & -3 \end{bmatrix}$$

$$\xrightarrow{r_3 := r_3 / (-3)} \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_1 := r_1 - r_3, r_2 := r_2 + 2r_3} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

So $x_1 + x_3 = 0$, $x_2 - x_3 = 0$ and $x_4 = 0$, x_3 is free. This implies that

$$x_1 = -x_3, x_2 = x_3, x_4 = 0 \text{ and } x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -x_3 \\ x_3 \\ x_3 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \end{bmatrix}.$$

Hence $\text{col}(A)^\perp = \text{span}\left\{\begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \end{bmatrix}\right\}$ and $\left\{\begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \end{bmatrix}\right\}$ is a basis for $\text{col}(A)^\perp$.

The dimension of $\text{col}(A)^\perp$ is 1.

- (d) Use Gram-Schmidt process to find an orthogonal basis for the column of the matrix A .

Solution:

$$\text{Let } w_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}, w_2 = \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix} \text{ and } w_3 = \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix}.$$

Gram-Schmidt process is

$$v_1 = w_1, v_2 = w_2 - \frac{w_2 \cdot v_1}{v_1 \cdot v_1} v_1 \text{ and } v_3 = w_3 - \frac{w_3 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{w_3 \cdot v_2}{v_2 \cdot v_2} v_2.$$

$$\text{So } v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}. \text{ Compute } w_2 \cdot v_1 = \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} = 3, v_1 \cdot v_1 =$$

$$\begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} = 3 \text{ and } v_2 = \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix} - \frac{3}{3} \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}.$$

$$\text{Compute } w_3 \cdot v_1 = \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} = 3, w_3 \cdot v_2 = \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} = 3,$$

$$v_2 \cdot v_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} = 3 \text{ and}$$

$$v_3 = w_3 - \frac{w_3 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{w_3 \cdot v_2}{v_2 \cdot v_2} v_2 = \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix} - \frac{3}{3} \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} - \frac{3}{3} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \\ = \begin{bmatrix} 2-1-1 \\ 0-1-0 \\ 2-0-1 \\ -1+1-1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix}. \text{ Hence } \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix} \right\} \text{ is an orthog-} \\ \text{onal basis for } \text{Col}(A).$$

- (e) Find an orthonormal basis for the column of the matrix A .

Solution:

Note that $\|v_1\| = \sqrt{v_1 \cdot v_1} = \sqrt{3}$, $\|v_2\| = \sqrt{v_2 \cdot v_2} = \sqrt{3}$ and

$$\|v_3\| = \sqrt{v_3 \cdot v_3} = \sqrt{3}. \text{ Hence } \left\{ \frac{v_1}{\|v_1\|}, \frac{v_2}{\|v_2\|}, \frac{v_3}{\|v_3\|} \right\} = \left\{ \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ 0 \\ -\frac{1}{\sqrt{3}} \end{bmatrix}, \begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}, \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{3}} \end{bmatrix} \right\}$$

is an orthonormal basis for $Col(A)$.

- (f) Find the orthogonal projection of $y = \begin{bmatrix} 7 \\ 3 \\ 10 \\ -2 \end{bmatrix}$ onto the column space of A and write $y = \hat{y} + z$ where $\hat{y} \in Col(A)$ and $z \in Col(A)^\perp$. Also find the shortest distance from y to $Col(A)$.

Solution: Since $\{v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, v_3 = \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix}\}$ is an orthogonal basis for $Col(A)$, $y = \hat{y} + z$ where $\hat{y} = \frac{y \cdot v_1}{v_1 \cdot v_1} v_1 + \frac{y \cdot v_2}{v_2 \cdot v_2} v_2 + \frac{y \cdot v_3}{v_3 \cdot v_3} v_3 \in Col(A)$ and $z = y - \hat{y} \in Col(A)^\perp$. Compute

$$y \cdot v_1 = \begin{bmatrix} 7 \\ 3 \\ 10 \\ -2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} = 7 + 3 + 0 + 2 = 12, v_1 \cdot v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} =$$

$$1 + 1 + 1 = 3, y \cdot v_2 = \begin{bmatrix} 7 \\ 3 \\ 10 \\ -2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} = 7 + 0 + 10 - 2 = 15,$$

$$v_2 \cdot v_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} = 3,$$

$$y \cdot v_3 = \begin{bmatrix} 7 \\ 3 \\ 10 \\ -2 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix} = 0 - 3 + 10 + 2 = 9, v_3 \cdot v_3 = \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix} = 3.$$

$$\text{So } \hat{y} = \frac{12}{3} \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} + \frac{(15)}{3} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} + \frac{9}{3} \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 4+5+0 \\ 4+0-3 \\ 0+5+3 \\ -4+5-3 \end{bmatrix} = \begin{bmatrix} 9 \\ 1 \\ 8 \\ -2 \end{bmatrix} \text{ and}$$

$$z = y - \hat{y} = \begin{bmatrix} 7 \\ 3 \\ 10 \\ -2 \end{bmatrix} - \begin{bmatrix} 9 \\ 1 \\ 8 \\ -2 \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \\ 2 \\ 0 \end{bmatrix}. \text{ Note that } z \in Col(A)^\perp = \text{span}\left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix} \right\}.$$

The shortest distance from y to $Col(A) = \|y - \hat{y}\| = \|z\| =$

$$\sqrt{(2)^2 + (-2)^2 + (2)^2 + (0)^2} = \sqrt{12}.$$

(g) Using previous result to explain why $Ax = y$ has no solution.

Solution: Since the orthogonal projection of y to $Col(A)$ is not y , this implies that y is not in $Col(A)$. So $Ax = y$ has no solution.

(h) Use orthogonal projection to find the least square solution of $Ax = y$.

Solution: The least square solution of $Ax = y$ is the solution of

$Ax = \hat{y} = \begin{bmatrix} 9 \\ 1 \\ 8 \\ -2 \end{bmatrix}$ where \hat{y} is the orthogonal projection of y onto

the column space of A (from part (f), we know $\hat{y} = \begin{bmatrix} 9 \\ 1 \\ 8 \\ -2 \end{bmatrix}$.)

Consider the augmented matrix

$$[A \hat{y}] = \left[\begin{array}{ccc|c} 1 & 2 & 2 & 9 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 2 & 8 \\ -1 & 0 & -1 & -2 \end{array} \right] \quad r_2 := r_2 - r_1, r_3 := r_3 + r_1 \quad \left[\begin{array}{ccc|c} 1 & 2 & 2 & 9 \\ 0 & -1 & -2 & -8 \\ 0 & 1 & 2 & 8 \\ 0 & 2 & 1 & 7 \end{array} \right]$$

$$r_3 := r_3 + r_2, r_4 := r_4 + r_1 \quad \left[\begin{array}{ccc|c} 1 & 2 & 2 & 9 \\ 0 & -1 & -2 & -8 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -3 & -9 \end{array} \right]$$

$$r_2 := -r_2, r_4 := r_4 / (-3), r_3 \leftrightarrow r_4 \quad \left[\begin{array}{ccc|c} 1 & 2 & 2 & 9 \\ 0 & 1 & 2 & 8 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$r_2 := r_2 - 2r_3, r_1 := r_1 - 2r_3 \quad \left[\begin{array}{ccc|c} 1 & 2 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$r_1 := r_1 - 2r_2 \quad \left[\begin{array}{ccc|c} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right].$$

So $x_1 = -1$, $x_2 = 2$, $x_3 = 3$ and the least square solution of

$$Ax = y \text{ is } x = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix}.$$

(i) Use normal equation to find the least square solution of $Ax = y$.

Solution: The normal equation is $A^T Ax = A^T y$. Compute $A^T A =$

$$\begin{bmatrix} 1 & 1 & 0 & -1 \\ 2 & 1 & 1 & 0 \\ 2 & 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \\ -1 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 3 & 3 & 3 \\ 3 & 6 & 6 \\ 3 & 6 & 9 \end{bmatrix}$$

$$\text{and } A^T y = \begin{bmatrix} 1 & 1 & 0 & -1 \\ 2 & 1 & 1 & 0 \\ 2 & 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} 7 \\ 3 \\ 10 \\ -2 \end{bmatrix} = \begin{bmatrix} 12 \\ 27 \\ 36 \end{bmatrix}.$$

So the normal equation $A^T Ax = A^T y$ is

$$\begin{bmatrix} 3 & 3 & 3 \\ 3 & 6 & 6 \\ 3 & 6 & 9 \end{bmatrix} x = \begin{bmatrix} 12 \\ 27 \\ 36 \end{bmatrix}.$$

Consider the augmented matrix $\begin{bmatrix} 3 & 3 & 3 & | & 12 \\ 3 & 6 & 6 & | & 27 \\ 3 & 6 & 9 & | & 36 \end{bmatrix} \sim$

$$r_2 := r_2 - r_1, r_3 := r_3 - r_1 \quad \begin{bmatrix} 3 & 3 & 3 & | & 12 \\ 0 & 3 & 3 & | & 15 \\ 0 & 3 & 6 & | & 24 \end{bmatrix}$$

$$\begin{aligned} &\sim r_3 := r_3 - r_2 \left[\begin{array}{ccc|c} 3 & 3 & 3 & 12 \\ 0 & 3 & 3 & 15 \\ 0 & 0 & 3 & 9 \end{array} \right] \sim r_1 := r_1/3, r_2 := r_2/3, r_3 := \\ &r_3/3 \left[\begin{array}{ccc|c} 1 & 1 & 1 & 4 \\ 0 & 1 & 1 & 5 \\ 0 & 0 & 1 & 3 \end{array} \right] \\ &\sim r_2 := r_2 - r_3, r_1 := r_1 - r_3 \left[\begin{array}{ccc|c} 1 & 1 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{array} \right] \\ &\sim r_1 := r_1 - r_2, \left[\begin{array}{ccc|c} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{array} \right] \\ &\text{So } x_1 = -1, x_2 = 2, x_3 = 3 \text{ and the least square solution of} \\ &Ax = y \text{ is } x = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix}. \end{aligned}$$

7. Find the equation $y = a + mx$ of the least square line that best fits the given data points. $(0, 1), (1, 1), (3, 2)$.

Solution: We try to solve the equations $1 = a, 1 = a + m, 2 = a + 3m$, that is,

$$a = 1, a + m = 1 \text{ and } a + 3m = 2. \text{ It corresponding to the linear system}$$

$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} a \\ m \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

Let $A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \end{bmatrix}$. We solve the normal equation

$$A^T A \begin{bmatrix} a \\ m \end{bmatrix} = A^T \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}.$$

Compute $A^T A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ 4 & 10 \end{bmatrix}$ and

$$A^T \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 7 \end{bmatrix}.$$

Consider the augmented matrix

$$\begin{aligned} & \begin{bmatrix} 3 & 4 & | & 4 \\ 4 & 10 & | & 7 \end{bmatrix} \sim r_2 := r_2 - \frac{4}{3}r_1 \begin{bmatrix} 3 & 4 & | & 4 \\ 0 & \frac{14}{3} & | & \frac{5}{3} \end{bmatrix} \\ & \sim r_2 := \frac{3}{14}r_2 \begin{bmatrix} 3 & 4 & | & 4 \\ 0 & 1 & | & \frac{5}{14} \end{bmatrix} \sim r_1 := r_1 - 4r_2 \begin{bmatrix} 3 & 0 & | & \frac{18}{7} \\ 0 & 1 & | & \frac{5}{14} \end{bmatrix} \\ & \sim r_1 := r_1/3 \begin{bmatrix} 1 & 0 & | & \frac{6}{7} \\ 0 & 1 & | & \frac{5}{14} \end{bmatrix} \end{aligned}$$

So the least square solution is $a = \frac{6}{7}$ and $m = \frac{5}{14}$. The equation $y = \frac{6}{7} + \frac{5}{14}x$ is the least square line that best fits the given data points. $(0, 1), (1, 1), (3, 2)$.

8. (a) Let $A = \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 2 & 3 & 4 \end{bmatrix}$. Find the inverse matrix of A if possible.

Solution: Consider the augmented matrix $[A \ I] = \begin{bmatrix} 3 & 6 & 7 & | & 1 & 0 & 0 \\ 0 & 2 & 1 & | & 0 & 1 & 0 \\ 2 & 3 & 4 & | & 0 & 0 & 1 \end{bmatrix}$

$$r_1 := r_1 - r_3 \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 2 & 1 & | & 0 & 1 & 0 \\ 2 & 3 & 4 & | & 0 & 0 & 1 \end{bmatrix}$$

$$r_3 := r_3 - 2r_1 \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 2 & 1 & | & 0 & 1 & 0 \\ 0 & -3 & -2 & | & -2 & 0 & 3 \end{bmatrix}$$

$$r_2 := r_2 + r_3 \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & -1 & -1 & | & -2 & 1 & 3 \\ 0 & -3 & -2 & | & -2 & 0 & 3 \end{bmatrix} \quad r_2 := -r_2 \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & -3 & -2 & | & -2 & 0 & 3 \end{bmatrix}$$

$$\begin{aligned}
r_3 &:= r_3 + 3r_2 \quad \left[\begin{array}{ccc|ccc} 1 & 3 & 3 & 1 & 0 & -1 \\ 0 & 1 & 1 & 2 & -1 & -3 \\ 0 & 0 & 1 & 4 & -3 & -6 \end{array} \right] \\
r_2 &:= r_2 - r_3, r_1 := r_1 - 3r_3 \quad \left[\begin{array}{ccc|ccc} 1 & 3 & 0 & -11 & 9 & 17 \\ 0 & 1 & 0 & -2 & 2 & 3 \\ 0 & 0 & 1 & 4 & -3 & -6 \end{array} \right] \\
r_1 &:= r_1 - 3r_2 \quad \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -5 & 3 & 8 \\ 0 & 1 & 0 & -2 & 2 & 3 \\ 0 & 0 & 1 & 4 & -3 & -6 \end{array} \right]. \\
\text{So } A^{-1} &= \begin{bmatrix} -5 & 3 & 8 \\ -2 & 2 & 3 \\ 4 & -3 & -6 \end{bmatrix}.
\end{aligned}$$

(b) Find the coordinates of the vector $(1, -1, 2)$ with respect to the basis B obtained from the column vectors of A .

Solution: The coordinate is $x = A^{-1} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -5 & 3 & 8 \\ -2 & 2 & 3 \\ 4 & -3 & -6 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} =$

$$\begin{bmatrix} 8 \\ 2 \\ -5 \end{bmatrix}.$$

9. Let $H = \left\{ \begin{bmatrix} a + 2b - c \\ a - b - 4c \\ a + b - 2c \end{bmatrix} : a, b, c \text{ any real numbers} \right\}$.

a. Explain why H is a subspace of \mathbb{R}^3 .

Solution: $\begin{bmatrix} a + 2b - c \\ a - b - 4c \\ a + b - 2c \end{bmatrix} = a \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} + c \begin{bmatrix} -1 \\ -4 \\ -2 \end{bmatrix}$

So $H = \text{Span}\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -4 \\ -2 \end{bmatrix} \right\}$ and H is a subspace.

b. Find a set of vectors that spans H .

Solution: $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -4 \\ -2 \end{bmatrix} \right\}$ spans the space H .

c. Find a basis for H .

Solution: Consider the matrix $A = \begin{bmatrix} 1 & 2 & -1 \\ 1 & -1 & -4 \\ 1 & 1 & -2 \end{bmatrix}$

$$r_2 := r_2 - r_1, r_3 := r_3 - r_1 \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & -3 \\ 0 & -1 & -1 \end{bmatrix}$$

$$r_2 := r_2 / (-3) \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 1 \\ 0 & -1 & -1 \end{bmatrix} \quad r_3 := r_3 + r_2 \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$

So the first two vectors are pivot vectors and $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \right\}$ is a basis.

The dimension of the subspace is 2.

d. What is the dimension of the subspace?

Solution: The dimension of the subspace is 2.

e. Find an orthogonal basis for H .

Solution: Let $u_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ and $u_2 = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$.

Then $v_1 = u_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ and $v_2 = u_2 - \frac{u_2 \cdot v_1}{v_1 \cdot v_1} v_1$. Compute $u_2 \cdot v_1 =$

$$\begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 2 - 1 + 1 = 2 \text{ and } v_1 \cdot v_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 1 + 1 + 1 = 3.$$

$v_2 = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} - \frac{2}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{4}{3} \\ -\frac{5}{3} \\ \frac{1}{3} \end{bmatrix}$. Thus $\left\{ v_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} \frac{4}{3} \\ -\frac{5}{3} \\ \frac{1}{3} \end{bmatrix} \right\}$ is an orthogonal basis for H . We can verify that $v_1 \cdot v_2 = 0$.

10. Determine if the following systems are consistent and if so give all

solutions in parametric vector form.

(a)

$$\begin{aligned}x_1 - 2x_2 &= 3 \\2x_1 - 7x_2 &= 0 \\-5x_1 + 8x_2 &= 5\end{aligned}$$

Solution: The augmented matrix is $\begin{bmatrix} 1 & -2 & 3 \\ 2 & -7 & 0 \\ -5 & 8 & 5 \end{bmatrix} \sim (r_2 := r_2 - 2r_1)$

$$\begin{bmatrix} 1 & -2 & 3 \\ 0 & -3 & -6 \\ -5 & 8 & 5 \end{bmatrix} \sim (r_3 := r_3 + 5r_1) \begin{bmatrix} 1 & -2 & 3 \\ 0 & -3 & -6 \\ 0 & -2 & 20 \end{bmatrix}$$

$\sim (r_2 := r_2 / -3, r_3 := r_3 / -2) \begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & 2 \\ 0 & 1 & -10 \end{bmatrix} \sim (r_3 := r_3 -$

$r_2) \begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & -12 \end{bmatrix}$. The last row implies that $0 = -12$ which is

impossible. So this system is inconsistent.

(b)

$$\begin{aligned}x_1 + 2x_2 - 3x_3 + x_4 &= 1 \\-x_1 - 2x_2 + 4x_3 - x_4 &= 6 \\-2x_1 - 4x_2 + 7x_3 - x_4 &= 1\end{aligned}$$

The augmented matrix is $\begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ -1 & -2 & 4 & -1 & 6 \\ -2 & -4 & 7 & -1 & 1 \end{bmatrix} \sim (r_2 := r_2 + r_1)$

$$\begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ 0 & 0 & 1 & 0 & 7 \\ -2 & -4 & 7 & -1 & 1 \end{bmatrix} \sim (r_3 := r_3 + 2r_1) \begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 1 & 1 & 3 \end{bmatrix}$$

$$\begin{aligned} &\sim (r_3 := r_3 - r_2) \begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 0 & 1 & -4 \\ 1 & 2 & -3 & 0 & 5 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 0 & 1 & -4 \end{bmatrix} \sim (r_1 := r_1 - r_3) \begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & -12 \\ 1 & 2 & 0 & 0 & 26 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 0 & 1 & -4 \end{bmatrix} \\ &\sim (r_1 := r_1 - r_3) \begin{bmatrix} 1 & 2 & -3 & 0 & 5 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 0 & 1 & -4 \end{bmatrix} \sim (r_1 := r_1 + 3r_2) \begin{bmatrix} 1 & 2 & 0 & 0 & 26 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 0 & 1 & -4 \end{bmatrix}. \end{aligned}$$

So x_2 is free. The solution is $x_1 = 26 - 2x_2$, $x_3 = 7$, $x_4 = -47$. Its

parametric vector form is
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 26 - 2x_2 \\ x_2 \\ 7 \\ -4 \end{bmatrix} = \begin{bmatrix} 26 \\ 0 \\ 7 \\ -4 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}.$$

11. Let $A = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 \\ 2 & -6 & 9 & -1 & 8 \\ 2 & -6 & 9 & -1 & 9 \\ -1 & 3 & -4 & 2 & -5 \end{bmatrix}$ which is row reduced to $\begin{bmatrix} 1 & -3 & -2 & -20 & -3 \\ 0 & 0 & 1 & 3 & 3 \\ 0 & 0 & 1 & 3 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

- (a) Find a basis for the column space of A
- (b) Find a basis for the nullspace of A
- (c) Find the rank of the matrix A
- (d) Find the dimension of the nullspace of A .

(e) Is $\begin{bmatrix} 1 \\ 4 \\ 3 \\ 1 \end{bmatrix}$ in the range of A ?

(e) Does $Ax = \begin{bmatrix} 0 \\ 3 \\ 2 \\ 0 \end{bmatrix}$ have any solution? Find a solution if it's solvable.

Solution: Consider the augmented matrix
$$\left[\begin{array}{ccccc|c|c} 1 & -3 & 4 & -2 & 5 & 1 & 0 \\ 2 & -6 & 9 & -1 & 8 & 4 & 3 \\ 2 & -6 & 9 & -1 & 9 & 3 & 2 \\ -1 & 3 & -4 & 2 & -5 & 1 & 0 \end{array} \right]$$

$$\begin{aligned}
& \widetilde{-2r_1 + r_2, -2r_1 + r_3, r_1 + r_4} \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & | & 1 & | & 0 \\ 0 & 0 & 1 & 3 & -2 & | & 2 & | & 3 \\ 0 & 0 & 1 & 3 & -1 & | & 1 & | & 2 \\ 0 & 0 & 0 & 0 & 0 & | & 2 & | & 0 \end{bmatrix} \\
& \widetilde{-r_2 + r_3} \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & | & 1 & | & 0 \\ 0 & 0 & 1 & 3 & -2 & | & 2 & | & 3 \\ 0 & 0 & 0 & 0 & 1 & | & -1 & | & -1 \\ 0 & 0 & 0 & 0 & 0 & | & 2 & | & 0 \end{bmatrix} \\
& \widetilde{2r_3 + r_2, -5r_3 + r_1} \begin{bmatrix} 1 & -3 & 4 & -2 & 0 & | & 6 & | & 5 \\ 0 & 0 & 1 & 3 & 0 & | & 0 & | & 1 \\ 0 & 0 & 0 & 0 & 1 & | & -1 & | & -1 \\ 0 & 0 & 0 & 0 & 0 & | & 2 & | & 0 \end{bmatrix} \\
& \widetilde{-4r_2 + r_1} \begin{bmatrix} 1 & -3 & 0 & -14 & 0 & | & 6 & | & 1 \\ 0 & 0 & 1 & 3 & 0 & | & 0 & | & 1 \\ 0 & 0 & 0 & 0 & 1 & | & -1 & | & -1 \\ 0 & 0 & 0 & 0 & 0 & | & 2 & | & 0 \end{bmatrix}.
\end{aligned}$$

So the first, third and fifth vector forms a basis for $\text{Col}(A)$, i.e. $\left\{ \begin{bmatrix} 1 \\ 2 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 4 \\ 9 \\ 9 \\ -4 \end{bmatrix}, \begin{bmatrix} 5 \\ 8 \\ 9 \\ -5 \end{bmatrix} \right\}$

is a basis for $\text{Col}(A)$. The rank of A is 3 and the dimension of the null space is $5 - 3 = 2$.

$x \in \text{Null}(A)$ if $x_1 - 3x_2 - 14x_4 = 0$, $x_3 + 3x_4 = 0$ and $x_5 = 0$. So

$$x = \begin{bmatrix} 3x_2 + 14x_4 \\ x_2 \\ -x_4 \\ x_4 \\ 0 \end{bmatrix} = x_2 \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 14 \\ 0 \\ -1 \\ 1 \\ 0 \end{bmatrix}. \text{ Thus } \left\{ \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 14 \\ 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} \right\} \text{ is a basis}$$

for $\text{NULL}(A)$.

From the result of row reduction, we can see that $Ax = \begin{bmatrix} 1 \\ 4 \\ 3 \\ 1 \end{bmatrix}$ is incon-

sistent (not solvable) and $\begin{bmatrix} 1 \\ 4 \\ 3 \\ 1 \end{bmatrix}$ is not in the range of A .

From the result of row reduction, we can see that $Ax = \begin{bmatrix} 0 \\ 3 \\ 2 \\ 0 \end{bmatrix}$ is solvable.

12. Determine if the columns of the matrix form a linearly independent set. Justify your answer.

$$\begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}, \begin{bmatrix} 1 & -2 \\ -2 & 4 \\ 3 & 6 \end{bmatrix}, \begin{bmatrix} -4 & -3 & 0 \\ 0 & -1 & 4 \\ 1 & 0 & 3 \\ 5 & 4 & 6 \end{bmatrix}, \begin{bmatrix} -4 & -3 & 1 & 5 & 1 \\ 2 & -1 & 4 & -1 & 2 \\ 1 & 2 & 3 & 6 & -3 \\ 5 & 4 & 6 & -3 & 2 \end{bmatrix}.$$

Solution: $\det \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = 2 - 1 = 1 \neq 0$. So the columns of the matrix form a linearly independent set.

$\begin{bmatrix} 1 & -2 \\ -2 & 4 \\ 3 & 6 \end{bmatrix}$. The second column vector is a multiple of the first column vector. So the columns of the matrix form a linearly dependent set.

$$\begin{array}{ccc}
& \begin{bmatrix} -4 & -3 & 0 \\ 0 & -1 & 4 \\ 1 & 0 & 3 \\ 5 & 4 & 6 \end{bmatrix} & \text{interchange } \widetilde{\text{first and third row}} & \begin{bmatrix} 1 & 0 & 3 \\ 0 & -1 & 4 \\ -4 & -3 & 0 \\ 5 & 4 & 6 \end{bmatrix} \\
r_3 + 4r_1, r_4 + (-5)r_1 & \begin{bmatrix} 1 & 0 & 3 \\ 0 & -1 & 4 \\ 0 & -3 & 12 \\ 0 & 4 & -9 \end{bmatrix} & & \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -4 \\ 0 & -3 & 12 \\ 0 & 4 & -9 \end{bmatrix} \\
& & & \widetilde{(-1)r_2} \\
r_3 + 3r_2, r_4 + (-4)r_2 & \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -4 \\ 0 & 0 & 0 \\ 0 & 0 & 7 \end{bmatrix} & \text{interchange } \widetilde{\text{3rd and 4th row}}, \frac{1}{7}r_4 & \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}
\end{array}$$

This matrix has three pivot vectors. So the columns of the matrix form a linearly independent set.

The column vectors of

$$\begin{bmatrix} -4 & -3 & 1 & 5 & 1 \\ 2 & -1 & 4 & -1 & 2 \\ 1 & 2 & 3 & 6 & -3 \\ 5 & 4 & 6 & -3 & 2 \end{bmatrix}$$

form a dependent set since we have five column vectors in R^4 .