## Linear Algebra (Math 2890) Solution to Final Review Problems

1. Let A be the matrix

.

$$A = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}.$$

(a) Prove that 
$$det(A - \lambda I) = (1 - \lambda)^2 (4 - \lambda)$$
.  
Solution: Compute  $A - \lambda I = \begin{bmatrix} 2 - \lambda & 1 & 1 \\ 1 & 2 - \lambda & 1 \\ 1 & 1 & 2 - \lambda \end{bmatrix}$  and  
 $det(A - \lambda I) = (2 - \lambda)^3 + 1 + 1 - (2 - \lambda) - (2 - \lambda) - (2 - \lambda) =$   
 $8 - 12\lambda + 6\lambda^2 - \lambda^3 + 2 - 6 + 3\lambda = -\lambda^3 + 6\lambda^2 - 9\lambda + 4 = (1 - \lambda)^2 (4 - \lambda).$ 

(b) Orthogonally diagonalizes the matrix A, giving an orthogonal matrix P and a diagonal matrix D such that  $A = PDP^t$ Solution: We know that the eigenvalues are 1,1 and 4.

When 
$$\lambda = 1, A - (1)I = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
  
 $x \in Null(A - I)$  if  $x_1 + x_2 + x_3 = 0$ . So  $x_1 = -x_2 - x_3$  and  
 $x = \begin{bmatrix} -x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \\ 1 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ . Thus  $\{w_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, w_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}\}$  is a basis of eigenvectors when  $\lambda = -1$ .

Now we use Gram-Schmidt process to find an orthogonal basis for Null(A - I).

Let 
$$v_1 = w_1 = \begin{bmatrix} -1\\ 1\\ 0\\ 0 \end{bmatrix}$$
 and  $v_2 = w_2 - \frac{w_2 \cdot v_1}{v_1 \cdot v_1} v_1$ . Compute  $w_2 \cdot v_1 = \begin{bmatrix} -1\\ 0\\ 1 \end{bmatrix} \cdot \begin{bmatrix} -1\\ 1\\ 0\\ 0 \end{bmatrix} = 1$  and  $v_1 \cdot v_1 = \begin{bmatrix} -1\\ 1\\ 0\\ 0 \end{bmatrix} \cdot \begin{bmatrix} -1\\ 1\\ 0\\ 0 \end{bmatrix} = 2$ .  
So  $v_2 = \begin{bmatrix} -1\\ 0\\ 1\\ 1 \end{bmatrix} - (\frac{1}{2}) \begin{bmatrix} -1\\ 1\\ 0\\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2}\\ -\frac{1}{2}\\ 1\\ 0 \end{bmatrix}$ .

Hence  $\{v_1 = \begin{vmatrix} -1 \\ 1 \\ 0 \end{vmatrix}$ ,  $v_2 = \begin{vmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{vmatrix}$ } is an orthogonal basis for Null(A -I). When  $\lambda = 4$ ,  $A - 4I = \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$  interchange  $r_1$  and  $r_2$ ,  $\begin{bmatrix} 1 & 1 & 1 \\ -2 & r_1 + r_2, -r_1 + r_3 \end{bmatrix} \begin{bmatrix} 1 & -2 & 1 \\ 0 & -3 & 3 \\ 0 & 3 & -3 \end{bmatrix}$  $\widetilde{r_2 + r_3, r_2/(-3)} \begin{vmatrix} 1 & -2 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{vmatrix} \widetilde{2r_2 + r_1} \begin{vmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{vmatrix} x \in Null(A - C)$ 4*I*) if  $x_1 - x_3 = 0$  and  $x_2 - x_3 = 0$ . So  $x = \begin{bmatrix} x_3 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ . Thus  $\{v_3 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}\}$  is a basis for Null(A-4I). So  $\{v_1 = \begin{bmatrix} -1\\1\\0 \end{bmatrix}, v_2 = \begin{bmatrix} -\frac{1}{2}\\-\frac{1}{2}\\1 \end{bmatrix}, v_3 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}\}$  is an orthogonal basis for  $R^3$  which are eigenvectors corresponding to  $\lambda = 1, \lambda = 1$  and  $\lambda = 4$ . Compute  $||v_1|| = \sqrt{2}, ||v_2|| = \sqrt{\frac{1}{4} + \frac{1}{4} + 1} = \sqrt{\frac{6}{4}} = \sqrt{\frac{3}{2}}$ and  $||v_3|| = \sqrt{3}$ . Thus  $\left\{ \frac{v_1}{||v_1||} = \begin{bmatrix} \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \frac{v_2}{||v_2||} = \begin{bmatrix} -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{6}} \end{bmatrix}, \frac{v_3}{||v_3||} = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} \right\}$  is an or-

thonormal basis for  $\mathbb{R}^3$  which are eigenvectors corresponding to

$$\begin{split} \lambda &= 1, \ \lambda = 1 \ \text{and} \ \lambda = 4. \\ \text{Finally, we have} \ A &= P \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix} P^T \ \text{where} \ P &= \begin{bmatrix} \frac{v_1}{||v_1||} & \frac{v_2}{||v_2||} & \frac{v_3}{||v_3||} \end{bmatrix} = \\ \begin{bmatrix} \frac{-1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{bmatrix}. \end{split}$$

(c) Write the quadratic form associated with A using variables  $x_1, x_2$ , and  $x_3$ ?

Solution: Recall that the quadratic form in  $x_1, x_2$  and  $x_3$  is  $Q_A(x) = x^T A x = 2x_1^2 + 2x_2^2 + 2x_3^2 + 2x_1x_2 + 2x_1x_3 + 2x_2x_3$ . (d) Find  $A^{-1}$ ,  $A^{10}$  and  $e^A$ 

(d) Find 
$$A^{-1}$$
,  $A^{10}$  and  $e^{21}$ .

Solution:Recall that 
$$A = PDP^{T}$$
. Then  $A^{-1} = PD^{-1}P^{T} = P\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1^{-1} & 0 \\ 0 & 0 & 4^{-1} \end{bmatrix} P^{T} = P\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} P^{T}$ .  
 $A^{10} = P\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4^{10} \end{bmatrix} P^{T}$  and  $e^{A} = P\begin{bmatrix} e & 0 & 0 \\ 0 & e & 0 \\ 0 & 0 & e^{4} \end{bmatrix} P^{T}$   
(e) What's  $A^{-5}(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix})$ ?

Solution: Note that  $v_3 = \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$  is an eigenvector with eigenvalue 4. So we have  $A(\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}) = 4\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$  and  $A^k(\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}) = 4^k\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$ . Hence  $A^{-5}(\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}) = 4^{-5}\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$ .

(f) What is  $\lim_{n \to \infty} A^{-n}$ ? Recall that  $A = PDP^T$  and  $A^{-n} = PD^{-n}P^T = P\begin{bmatrix} 1 & 0 & 0\\ 0 & 1^{-n} & 0\\ 0 & 0 & 4^{-n} \end{bmatrix} P^T = P\begin{bmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 4^{-n} \end{bmatrix} P^T$ . Note that  $\lim_{n \to \infty} 4^{-n} = PD^{-n}P^T$ .

0. So we have 
$$\lim_{n\to\infty} A^{-n} = P \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} P^T$$

- 2. Classify the quadratic forms for the following quadratic forms. Make a change of variable x = Py, that transforms the quadratic form into one with no cross term. Also write the new quadratic form.
  - (a)  $9x_1^2 8x_1x_2 + 3x_2^2$ . Let  $Q(x_1, x_2) = 9x_1^2 - 8x_1x_2 + 3x_2^2 = x^T \begin{vmatrix} 9 & -4 \\ -4 & 3 \end{vmatrix} x$  and A = $\begin{vmatrix} 9 & -4 \\ -4 & 3 \end{vmatrix}$ . We want to orthogonally diagonalizes A. Compute  $A - \lambda I = \begin{bmatrix} 9 - \lambda & -4 \\ -4 & 3 - \lambda \end{bmatrix}$  and  $det(A - \lambda I) = (9 - \lambda)(3 - \lambda) - 16 = \lambda^2 - 12\lambda + 27 - 16 = \lambda^2 - 12\lambda + 11 = (\lambda - 1)(\lambda - 11).$ So  $\lambda = 1$  or  $\lambda = 11$ . Since the eigenvalues of A are all positive, we know that the quadratic form is positive definite. Now we diagonalize A.  $\lambda = 1: A - 1 \cdot I = \begin{bmatrix} 9 - 1 & -4 \\ -4 & 3 - 1 \end{bmatrix} = \begin{bmatrix} 8 & -4 \\ -4 & 2 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix}.$  So  $x \in Null(A-1 \cdot I)$  iff  $2x_1 - x_2 = 0$ . So  $x_2 = 2x_1$  and  $x = \begin{vmatrix} x_1 \\ 2x_1 \end{vmatrix} =$  $x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ . So  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$  is an eigenvector corresponding to eigenvalue  $\lambda =$  $\lambda = 11: A - 11 \cdot I = \begin{bmatrix} 9 - 11 & -4 \\ -4 & 3 - 11 \end{bmatrix} = \begin{bmatrix} -2 & -4 \\ -4 & -8 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}.$ So  $x \in Null(A - 11 \cdot I)$  iff  $x_1 + 2x_2 = 0$ . So  $x_1 = -2x_2$  and  $x = \begin{bmatrix} -2x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ . So  $\begin{bmatrix} -2 \\ 1 \end{bmatrix}$  is an eigenvector corresponding to eigenvalue  $\lambda$  = Now  $\{v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}\}$  is an orthogonal basis. Compute  $||v_1|| = \sqrt{5}$  and  $||v_2|| = \sqrt{5}$ . Thus  $\left\{\frac{v_1}{||v_1||} = \begin{vmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{vmatrix}, \frac{v_2}{||v_2||} = \begin{vmatrix} \frac{-2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{vmatrix}\right\}$  is

an orthonormal basis of eigenvectors. So we have  $A = P \begin{bmatrix} 1 & 0 \\ 0 & 11 \end{bmatrix} P^T$ 

where  $P = \begin{vmatrix} \frac{1}{\sqrt{5}} & \frac{-2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{vmatrix}$ . Now  $Q(x) = x^T A x = x^T P \begin{bmatrix} 1 & 0 \\ 0 & 11 \end{bmatrix} P^T x = y^T \begin{bmatrix} 1 & 0 \\ 0 & 11 \end{bmatrix} y = y_1^2 + y_1$  $11y_2^2$  if  $y = P^T x$ . So  $Py = PP^T x$ , x = Py and  $P = \begin{vmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{-2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{vmatrix}$ . Note that we have used the fact that  $PP^T = I$ .

(b) 
$$-5x_1^2 + 4x_1x_2 - 2x_2^2$$

Let 
$$Q(x_1, x_2) = -5x_1^2 + 4x_1x_2 - 2x_2^2 = x^T \begin{bmatrix} -5 & 2\\ 2 & -2 \end{bmatrix} x$$
 and  $A = \begin{bmatrix} -5 & 2\\ 2 & -2 \end{bmatrix} x$ 

 $\begin{bmatrix} -5 & 2 \\ 2 & -2 \end{bmatrix}$ . We want to orthogonally diagonalizes A.

Compute  $A - \lambda I = \begin{bmatrix} -5 - \lambda & 2\\ 2 & -2 - \lambda \end{bmatrix}$  and  $det(A - \lambda I) = (-5 - \lambda)$  $\lambda(-2 - \lambda) - 4 = \lambda^2 + 7\lambda + 10 - 4 = \lambda^2 + 7\lambda + 6 = (\lambda + 1)(\lambda + 6).$ So  $\lambda = -1$  or  $\lambda = -6$ . Since the eigenvalues of A are all negative, we know that the quadratic form is negative definite. Now we diagonalize A.

 $\lambda = -1: A - (-1) \cdot I = \begin{bmatrix} -5 - (-1) & 2 \\ 2 & -2 - (-1) \end{bmatrix} = \begin{bmatrix} -4 & 2 \\ 2 & -1 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix}.$ So  $x \in Null(A - 1 \cdot I)$  iff  $2x_1 - x_2 = 0$ . So  $x_2 = 2x_1$  and  $x = \begin{bmatrix} x_1 \\ 2x_1 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$  So  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$  is an eigenvector corresponding to eigenvalue  $\lambda =$  $\lambda = -6: A - (-6) \cdot I = \begin{bmatrix} -5 - (-6) & 2\\ 2 & (-2) - (-6) \end{bmatrix} = \begin{bmatrix} 1 & 2\\ 2 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 2\\ 0 & 0 \end{bmatrix}.$ So  $x \in Null(A - 11 \cdot I)$  iff  $x_1 + 2x_2 = 0$ . So  $x_1 = -2x_2$  and  $x = \begin{bmatrix} -2x_2\\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} -2\\ 1 \end{bmatrix}.$  So  $\begin{bmatrix} -2\\ 1 \end{bmatrix}$  is an eigenvector corresponding Now  $\{v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}\}$  is an orthogonal basis. Compute

 $||v_1|| = \sqrt{5}$  and  $||v_2|| = \sqrt{5}$ . Thus  $\left\{\frac{v_1}{||v_1||} = \begin{vmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{vmatrix}$ ,  $\frac{v_2}{||v_2||} = \begin{vmatrix} \frac{-2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{vmatrix}$ } is an orthonormal basis of eigenvectors. So we have  $A = P \begin{bmatrix} -1 & 0 \\ 0 & -6 \end{bmatrix} P^T$ where  $P = \begin{vmatrix} \frac{1}{\sqrt{5}} & \frac{-2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{vmatrix}$ . Now  $Q(x) = x^T A x = x^T P \begin{bmatrix} -1 & 0 \\ 0 & -6 \end{bmatrix} P^T x = y^T \begin{bmatrix} -1 & 0 \\ 0 & -6 \end{bmatrix} y = -y_1^2 - 6y_2^2$  if  $y = P^T x$ . So  $Py = PP^T x$ , x = Py and  $P = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{-2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}$ . (c)  $8x_1^2 + 6x_1x_2$ . Let  $Q(x_1, x_2) = 8x_1^2 + 6x_1x_2 = x^T \begin{vmatrix} 8 & 3 \\ 3 & 0 \end{vmatrix} x$  and  $A = \begin{vmatrix} 8 & 3 \\ 3 & 0 \end{vmatrix}$ . We want to orthogonally diagonalizes Compute  $A - \lambda I = \begin{bmatrix} 8 - \lambda & 3 \\ 3 & 0 - \lambda \end{bmatrix}$  and  $det(A - \lambda I) = (8 - \lambda) \cdot$  $(-\lambda) - 9 = \lambda^2 - 8\lambda - 9 = (\lambda + 1)(\lambda - 9)$ . So  $\lambda = -1$  or  $\lambda = 9$ . Since A has positive and negative eigenvalues, we know that the quadratic form is indefinite. Now we diagonalize A.  $\lambda = -1: A - (-1) \cdot I = \begin{bmatrix} 8 - (-1) & 3 \\ 3 & 0 - (-1) \end{bmatrix} = \begin{bmatrix} 9 & 3 \\ 3 & 1 \end{bmatrix} \sim \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix}.$ So  $x \in Null(A - 1 \cdot I)$  iff  $3x_1 + x_2 = 0$ . So  $x_2 = -3x_1$  and  $x = \begin{bmatrix} x_1 \\ -3x_1 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ -3 \end{bmatrix}$ . So  $\begin{bmatrix} 1 \\ -3 \end{bmatrix}$  is an eigenvector corresponding to eigenvalue  $\lambda =$  $\lambda = 9: A - 9 \cdot I = \begin{bmatrix} 8 - 9 & 3 \\ 3 & 0 - 9 \end{bmatrix} = \begin{bmatrix} -1 & 3 \\ 3 & -9 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 \\ 0 & 0 \end{bmatrix}.$  So  $x \in Null(A - 9 \cdot I)$  iff  $x_1 - 3x_2 = 0$ . So  $x_1 = 3x_2$  and  $x = \begin{vmatrix} 3x_2 \\ x_2 \end{vmatrix} =$  $x_2 \begin{vmatrix} 3 \\ 1 \end{vmatrix}$ . So  $\begin{vmatrix} 3 \\ 1 \end{vmatrix}$  is an eigenvector corresponding to eigenvalue  $\lambda =$ 

Now  $\{v_1 = \begin{bmatrix} 1 \\ -3 \end{bmatrix}, v_2 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}\}$  is an orthogonal basis. Compute

$$\begin{aligned} ||v_1|| &= \sqrt{10} \text{ and } ||v_2|| &= \sqrt{10}. \quad \text{Thus } \left\{ \frac{v_1}{||v_1||} &= \begin{bmatrix} \frac{1}{\sqrt{10}} \\ \frac{-3}{\sqrt{10}} \end{bmatrix}, \frac{v_2}{||v_2||} &= \\ \begin{bmatrix} \frac{3}{\sqrt{10}} \\ \frac{1}{\sqrt{10}} \end{bmatrix} \right\} \text{ is an orthonormal basis of eigenvectors. So we have } A = \\ P \begin{bmatrix} -1 & 0 \\ 0 & 9 \end{bmatrix} P^T \text{ where } P = \begin{bmatrix} \frac{1}{\sqrt{10}} & \frac{-3}{\sqrt{10}} \\ \frac{3}{\sqrt{10}} & \frac{1}{\sqrt{10}} \end{bmatrix}. \\ \text{Now } Q(x) &= x^T A x = x^T P \begin{bmatrix} -1 & 0 \\ 0 & 9 \end{bmatrix} P^T x = y^T \begin{bmatrix} -1 & 0 \\ 0 & 9 \end{bmatrix} y = -y_1^2 + \\ 9y_2^2 \text{ if } y = P^T x. \text{ So } Py = PP^T x, x = Py \text{ and } P \begin{bmatrix} \frac{1}{\sqrt{10}} & \frac{-3}{\sqrt{10}} \\ \frac{3}{\sqrt{10}} & \frac{1}{\sqrt{10}} \end{bmatrix}. \end{aligned}$$

3. (a) Find a  $3 \times 3$  matrix A which is not diagonalizable?

Solution: Let  $A = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ . Then  $det(A - \lambda I) = -\lambda^3$  and the eigenvalues of A are zero.

$$A - 0 \cdot I = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$
 The eigenvector  $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$  satisfies  $x_2 = 0$  and  $x_3 = 0$ . The eigenvector is  $x = \begin{bmatrix} x_1 \\ 0 \\ 0 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$  So there is only one eigenvector for  $A$  and  $A$  is not diagonalizable.

(b) Give an example of a  $2 \times 2$  matrix which is diagonalizable but not orthogonally diagonalizable?

Solution: Let  $A = \begin{bmatrix} 1 & 4 \\ 1 & 1 \end{bmatrix}$ . Then  $det(A - \lambda I) == \begin{bmatrix} 1 - \lambda & 4 \\ 1 & 1 - \lambda \end{bmatrix} = (1 - \lambda)^2 - 4 = (1 - \lambda)^2 - 2^2 = (1 - \lambda - 2)(1 - \lambda + 2) = (-\lambda - 1)(3 - \lambda)$ . So A has two distinct eigenvalues and A is diagonalizable. But A is not symmetric. So A is not orthogonally diagonalizable.

4. Let 
$$A = \begin{bmatrix} 1 & 2 & 2 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \\ -1 & 0 & -1 \end{bmatrix}$$
.  
(a) Find the condition on  $b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$  such that  $Ax = b$  is solvable.  
Solution:  
Consider the augmented matrix  $\begin{bmatrix} A & b \end{bmatrix} = \begin{bmatrix} 1 & 2 & 2 & | & b_1 \\ 1 & 1 & 0 & | & b_2 \\ 0 & 1 & 2 & | & b_3 \\ -1 & 0 & -1 & | & b_4 \end{bmatrix}$   
 $a_2 := \widetilde{a_2 + (-1)}a_1 \begin{bmatrix} 1 & 2 & 2 & | & b_1 \\ 0 & -1 & -2 & | & b_1 \\ 0 & -1 & -2 & | & b_2 \\ 0 & 1 & 2 & | & b_3 \\ -1 & 0 & -1 & | & b_4 \end{bmatrix}$   
 $a_4 := \widetilde{a_4} + a_1 \begin{bmatrix} 1 & 2 & 2 & | & b_1 \\ 0 & -1 & -2 & | & b_2 \\ 0 & -1 & -2 & | & b_2 \\ 0 & 1 & 2 & | & b_3 \\ 0 & 2 & 1 & | & b_4 + b_1 \end{bmatrix}$   
 $a_2 := -a_2 \begin{bmatrix} 1 & 2 & 2 & | & b_1 \\ 0 & 1 & 2 & | & b_3 \\ 0 & 2 & 1 & | & b_4 + b_1 \end{bmatrix}$   
 $a_3 := a_3 - \widetilde{a_{2, a_4}} := a_4 - 2a_2 \begin{bmatrix} 1 & 2 & 2 & | & b_1 \\ 0 & 1 & 2 & | & -b_2 + b_1 \\ 0 & 1 & 2 & | & -b_2 + b_1 \\ 0 & 0 & | & b_3 + b_2 - b_1 \\ 0 & 0 & | & b_3 + b_2 - b_1 \\ 0 & 0 & -3 & | & b_4 - b_1 + 2 b_2 \end{bmatrix}$ 

$$\overbrace{a_3 \leftrightarrow a_4} \begin{bmatrix}
1 & 2 & 2 & b_1 \\
0 & 1 & 2 & -b_2 + b_1 \\
0 & 0 & -3 & b_4 - b_1 + 2 & b_2 \\
0 & 0 & 0 & b_3 + b_2 - b_1
\end{bmatrix}$$

From here, we can see that Ax = b has a solution if  $b_3 + b_2 - b_1 = 0$ .

(b) What is the column space of A? Solution:

The column space is the subspace spanned by the column vectors. From the computation in (a), we know that the column vectors of  $\begin{bmatrix} 1 & 1 & 2 & 2 & 2 \end{bmatrix}$ 

A are independent. So 
$$Col(A) = span \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \\ 2 \\ -1 \end{bmatrix} \right\}.$$

(c) Describe the subspace  $col(A)^{\perp}$  and find an basis for  $col(A)^{\perp}$ . Solution:  $col(A)^{\perp} = \{x | x \cdot y = 0 \text{ for all } y \in col(A)\}$ 

$$= \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} + \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix} = 0, \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix} = 0, \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix} = 0 \right\}$$
$$= \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} | x_1 + x_2 - x_4 = 0, 2x_1 + x_2 + x_3 = 0, 2x_1 + 2x_3 - x_4 = 0 \right\}$$
$$Consider \begin{bmatrix} 1 & 1 & 0 & -1 \\ 2 & 1 & 1 & 0 \\ 2 & 0 & 2 & -1 \end{bmatrix} r_2 := r_2 - 2r_1 \begin{bmatrix} 1 & 1 & 0 & -1 \\ 0 & -1 & 1 & 2 \\ 2 & 0 & 2 & -1 \end{bmatrix}$$
$$r_3 := r_3 - 2r_1 \begin{bmatrix} 1 & 1 & 0 & -1 \\ 0 & -1 & 1 & 2 \\ 0 & -2 & 2 & 1 \end{bmatrix} r_2 := -r_2 \begin{bmatrix} 1 & 1 & 0 & -1 \\ 0 & 1 & -1 & -2 \\ 0 & -2 & 2 & 1 \end{bmatrix}$$

$$\begin{split} & \overbrace{r_3:=r_3+2r_2} \left[ \begin{array}{ccccc} 1 & 1 & 0 & -1 \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & -3 \\ \end{array} \right] r_1:=r_1-r_2 \left[ \begin{array}{ccccc} 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & -3 \\ \end{array} \right] \\ & \overbrace{r_3:=r_3/(-3)} \left[ \begin{array}{cccccc} 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & 1 \\ \end{array} \right] r_1:=r_1-r_3, r_2:=r_2+2r_3 \left[ \begin{array}{cccccc} 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ \end{array} \right] \\ & \operatorname{So} x_1+x_3=0, x_2-x_3=0 \text{ and } x_4=0, x_3 \text{ is free. This implies that} \\ & x_1=-x_3, x_2=x_3 \ , x_4=0 \text{ and } x=\left[ \begin{array}{c} x_1 \\ x_2 \\ x_3 \\ x_4 \\ \end{array} \right] = \left[ \begin{array}{c} -x_3 \\ x_3 \\ x_3 \\ 0 \\ \end{array} \right] = x_3 \left[ \begin{array}{c} -1 \\ 1 \\ 0 \\ \end{array} \right] . \\ & \operatorname{Hence} \ col(A)^{\perp}=span\{\left[ \begin{array}{c} -1 \\ 1 \\ 1 \\ 0 \\ \end{array} \right]\} \text{ and } \{ \left[ \begin{array}{c} -1 \\ 1 \\ 1 \\ 0 \\ \end{array} \right] \} \text{ is a basis for } col(A)^{\perp}. \\ & \operatorname{The \ dimension \ of \ col(A)^{\perp} \text{ is } 1. \end{split} \right] \end{split}$$

(d) Use Gram-Schmidt process to find an orthogonal basis for the column of the matrix A. Solution:

Solution:  
Let 
$$w_1 = \begin{bmatrix} 1\\ 1\\ 0\\ -1 \end{bmatrix}$$
,  $w_2 = \begin{bmatrix} 2\\ 1\\ 1\\ 0 \end{bmatrix}$  and  $w_3 = \begin{bmatrix} 2\\ 0\\ 2\\ -1 \end{bmatrix}$ .  
Gram-Schmidt process is  
 $v_1 = w_1, v_2 = w_2 - \frac{w_2 \cdot v_1}{v_1 \cdot v_1} v_1$  and  $v_3 = w_3 - \frac{w_3 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{w_3 \cdot v_2}{v_2 \cdot v_2} v_2$ .  
So  $v_1 = \begin{bmatrix} 1\\ 1\\ 0\\ -1 \end{bmatrix}$ . Compute  $w_2 \cdot v_1 = \begin{bmatrix} 2\\ 1\\ 1\\ 0\\ -1 \end{bmatrix} = 3$ ,  $v_1 \cdot v_1 = \begin{bmatrix} 1\\ 0\\ -1\\ 1\\ 0\\ -1 \end{bmatrix} = 3$  and  $v_2 = \begin{bmatrix} 2\\ 1\\ 1\\ 0\\ -1\\ 1 \end{bmatrix} - \frac{3}{3} \begin{bmatrix} 1\\ 1\\ 0\\ -1\\ 1 \end{bmatrix} = \begin{bmatrix} 1\\ 0\\ 1\\ 1\\ 1 \end{bmatrix}$ .  
Compute  $w_3 \cdot v_1 = \begin{bmatrix} 2\\ 0\\ 2\\ -1\\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1\\ 0\\ 2\\ -1\\ 1 \end{bmatrix} + \begin{bmatrix} 1\\ 0\\ 0\\ -1\\ 1 \end{bmatrix} = 3$ ,  $w_3 \cdot v_2 = \begin{bmatrix} 2\\ 0\\ 2\\ -1\\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1\\ 0\\ 1\\ 1\\ 1 \end{bmatrix} = 3$ ,  
 $v_2 \cdot v_2 = \begin{bmatrix} 1\\ 0\\ 1\\ 1\\ 1\\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1\\ 0\\ 1\\ 1\\ 1\\ 1 \end{bmatrix} = 3$  and  
 $v_3 = w_3 - \frac{w_3 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{w_3 \cdot v_2}{v_2 \cdot v_2} v_2 = \begin{bmatrix} 2\\ 0\\ 2\\ -1\\ 1 \end{bmatrix} - \frac{3}{3} \begin{bmatrix} 1\\ 1\\ 0\\ -1\\ 1 \end{bmatrix} - \frac{3}{3} \begin{bmatrix} 1\\ 0\\ 1\\ 1\\ 1 \end{bmatrix}$ 

$$= \begin{bmatrix} 2^{-1-1} \\ 0^{-1-0} \\ 2^{-0-1} \\ -1+1-1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix}. \text{ Hence } \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \\ 1 \end{bmatrix} \right\} \text{ is an orthog-orthogonal basis for } Col(A).$$

(e) Find an orthonormal basis for the column of the matrix A. Solution: Note that  $||u|||_{-\infty} = \sqrt{2} ||u|||_{-\infty} = \sqrt{2}$ 

Note that 
$$||v_1|| = \sqrt{v_1 \cdot v_1} = \sqrt{3}$$
,  $||v_2|| = \sqrt{v_2 \cdot v_2} = \sqrt{3}$  and  
 $||v_3|| = \sqrt{v_3 \cdot v_3} = \sqrt{3}$ . Hence  $\{\frac{v_1}{||v_1||}, \frac{v_2}{||v_2||}, \frac{v_3}{||v_3||}\} = \{\begin{bmatrix}\frac{1}{\sqrt{3}}\\ \frac{1}{\sqrt{3}}\\ 0\\ -\frac{1}{\sqrt{3}}\end{bmatrix}, \begin{bmatrix}\frac{1}{\sqrt{3}}\\ 0\\ \frac{1}{\sqrt{3}}\\ \frac{1}{\sqrt{3}}\end{bmatrix}, \begin{bmatrix}0\\ -\frac{1}{\sqrt{3}}\\ \frac{1}{\sqrt{3}}\\ -\frac{1}{\sqrt{3}}\end{bmatrix}\}$ 

is an orthonormal basis for Col(A).

(f) Find the orthogonal projection of  $y = \begin{bmatrix} 1 \\ 3 \\ 10 \\ -2 \end{bmatrix}$  onto the column

space of A and write  $y = \hat{y} + z$  where  $\hat{y} \in col(A)$  and  $z \in col(A)^{\perp}$ . Also find the shortest distance from y to Col(A).

Solution: Since  $\{v_1 = \begin{bmatrix} 1\\ 1\\ 0\\ -1 \end{bmatrix}, v_2 = \begin{bmatrix} 1\\ 0\\ 1\\ 1 \end{bmatrix}, v_3 = \begin{bmatrix} 0\\ -1\\ 1\\ -1 \end{bmatrix}\}$  is an orthogonal basis for  $Col(A), y = \hat{y} + z$  where  $\hat{y} = \frac{y \cdot v_1}{v_1 \cdot v_1}v_1 + \frac{y \cdot v_2}{v_2 \cdot v_2}v_2 + \frac{y \cdot v_3}{v_3 \cdot v_3}v_3 \in Col(A)$  and  $z = y - \hat{y} \in Col(A)^{\perp}$ . Compute  $y \cdot v_1 = \begin{bmatrix} 7\\ 3\\ 10\\ -2 \end{bmatrix} \cdot \begin{bmatrix} 1\\ 1\\ 0\\ -1 \end{bmatrix} = 7 + 3 + 0 + 2 = 12, v_1 \cdot v_1 = \begin{bmatrix} 1\\ 1\\ 0\\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1\\ 1\\ 0\\ -1 \end{bmatrix} = 1$  $1 + 1 + 1 = 3, y \cdot v_2 = \begin{bmatrix} 7\\ 3\\ 10\\ -2 \end{bmatrix} \cdot \begin{bmatrix} 7\\ 3\\ 10\\ -2 \end{bmatrix} \cdot \begin{bmatrix} 1\\ 0\\ 1\\ 1\\ 1 \end{bmatrix} = 7 + 0 + 10 - 2 = 15,$  $v_2 \cdot v_2 = \begin{bmatrix} 1\\ 0\\ 1\\ 1\\ -1 \end{bmatrix} \cdot \begin{bmatrix} 0\\ -1\\ 1\\ 1\\ -1 \end{bmatrix} = 3,$  $y \cdot v_3 = \begin{bmatrix} 7\\ 3\\ 10\\ -2 \end{bmatrix} \cdot \begin{bmatrix} 0\\ -1\\ 1\\ -1\\ -1 \end{bmatrix} = 0 - 3 + 10 + 2 = 9, v_3 \cdot v_3 = \begin{bmatrix} 0\\ -1\\ 1\\ -1\\ -1\\ -1 \end{bmatrix} \cdot \begin{bmatrix} 0\\ -1\\ 1\\ -1\\ -1\\ -1 \end{bmatrix} = 3.$ 

So 
$$\widehat{y} = \frac{12}{3} \begin{bmatrix} 1\\1\\0\\-1 \end{bmatrix} + \frac{(15)}{3} \begin{bmatrix} 1\\0\\1\\1\\1 \end{bmatrix} + \frac{9}{3} \begin{bmatrix} 0\\-1\\1\\-1\\-1 \end{bmatrix} = \begin{bmatrix} 4+5+0\\4+0-3\\0+5+3\\-4+5-3 \end{bmatrix} = \begin{bmatrix} 9\\1\\8\\-2 \end{bmatrix}$$
 and  
 $z = y - \widehat{y} = \begin{bmatrix} 7\\3\\10\\-2 \end{bmatrix} - \begin{bmatrix} 9\\1\\8\\-2 \end{bmatrix} = \begin{bmatrix} 2\\-2\\2\\0 \end{bmatrix}$ . Note that  $z \in Col(A)^{\perp} =$   
 $span\{\begin{bmatrix} 1\\-1\\1\\0 \end{bmatrix}\}.$   
The shortest distance from  $y$  to  $Col(A) = ||y - \widehat{y}|| = ||z|| =$ 

The shortest distance from y to  $Col(A) = ||y - \hat{y}|| = ||z|| = \sqrt{(2)^2 + (-2)^2 + (2)^2 + (0)^2} = \sqrt{12}.$ 

- (g) Using previous result to explain why Ax = y has no solution. Solution: Since the orthogonal projection of y to Col(A) is not y, this implies that y is not in Col(A). So Ax = y has no solution.
- (h) Use orthogonal projection to find the least square solution of Ax = y.

Solution: The least square solution of Ax = y is the solution of  $Ax = \hat{y} = \begin{bmatrix} 9\\1\\8\\-2 \end{bmatrix}$  where  $\hat{y}$  is the orthogonal projection of y onto

the column space of A (from part (f), we know  $\hat{y} = \begin{bmatrix} 9\\1\\8\\-2 \end{bmatrix}$ .) Consider the augmented matrix

$$\begin{bmatrix} A \ \hat{y} \end{bmatrix} = \begin{bmatrix} 1 & 2 & 2 & | & 9 \\ 1 & 1 & 0 & | & 1 \\ 0 & 1 & 2 & | & 8 \\ -1 & 0 & -1 & | & -2 \end{bmatrix} r_2 := r_2 - \tilde{r_1, r_3} := r_3 + r_1 \begin{bmatrix} 1 & 2 & 2 & | & 9 \\ 0 & -1 & -2 & | & -8 \\ 0 & 1 & 2 & | & 8 \\ 0 & 2 & 1 & | & 7 \end{bmatrix}$$
$$r_3 := r_3 + \tilde{r_2, r_4} := r_4 + r_1 \begin{bmatrix} 1 & 2 & 2 & | & 9 \\ 0 & -1 & -2 & | & -8 \\ 0 & 0 & -1 & -2 & | & -8 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & -3 & | & -9 \end{bmatrix}$$

$$r_{2} := -r_{2}, r_{4} := \overline{r_{4}/(-3)}, r_{3} \leftrightarrow r_{4} \begin{bmatrix} 1 & 2 & 2 & | & 9 \\ 0 & 1 & 2 & | & 8 \\ 0 & 0 & 1 & | & 3 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$r_{2} := r_{2} - 2r_{3}, r_{1} := r_{1} - 2r_{3} \begin{bmatrix} 1 & 2 & 0 & | & 3 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 3 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$
  
$$r_{1} := r_{1} - 2r_{2} \begin{bmatrix} 1 & 0 & 0 & | & -1 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 3 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$
  
So  $x_{1} = -1, x_{2} = 2, x_{3} = 3$  and the least square solution of  
 $Ax = y$  is  $x = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix}$ .

(i) Use normal equation to find the least square solution of Ax = y. Solution: The normal equation is  $A^TAx = A^Ty$ . Compute  $A^TA =$ 

$$\begin{bmatrix} 1 & 1 & 0 & -1 \\ 2 & 1 & 1 & 0 \\ 2 & 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \\ -1 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 3 & 3 & 3 \\ 3 & 6 & 6 \\ 3 & 6 & 9 \end{bmatrix}$$
  
and  $A^{T}y = \begin{bmatrix} 1 & 1 & 0 & -1 \\ 2 & 1 & 1 & 0 \\ 2 & 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} 7 \\ 3 \\ 10 \\ -2 \end{bmatrix} = \begin{bmatrix} 12 \\ 27 \\ 36 \end{bmatrix}.$   
So the normal equation  $A^{T}Ax = A^{T}y$  is  
$$\begin{bmatrix} 3 & 3 & 3 \\ 3 & 6 & 6 \\ 3 & 6 & 9 \end{bmatrix} x = \begin{bmatrix} 12 \\ 27 \\ 36 \end{bmatrix}.$$
  
Consider the augmented matrix 
$$\begin{bmatrix} 3 & 3 & 3 & | 12 \\ 3 & 6 & 6 & | 27 \\ 3 & 6 & 9 & | 36 \end{bmatrix} \sim$$

$$\begin{aligned} r_{2} &:= r_{2} - r_{1}, r_{3} := r_{3} - r_{1} \begin{bmatrix} 3 & 3 & 3 & | 12 \\ 0 & 3 & 3 & | 15 \\ 0 & 3 & 6 & | 24 \end{bmatrix} \\ &\sim r_{3} &:= r_{3} - r_{2} \begin{bmatrix} 3 & 3 & 3 & | 12 \\ 0 & 3 & 3 & | 15 \\ 0 & 0 & 3 & | 9 \end{bmatrix} \sim r_{1} := r_{1}/3, r_{2} := r_{2}/3, r_{3} := r_{3}/3 \begin{bmatrix} 1 & 1 & 1 & | 4 \\ 0 & 1 & 1 & | 5 \\ 0 & 0 & 1 & | 3 \end{bmatrix} \\ &\sim r_{2} := r_{2} - r_{3}, r_{1} := r_{1} - r_{3} \begin{bmatrix} 1 & 1 & 0 & | 1 \\ 0 & 1 & 0 & | 2 \\ 0 & 0 & 1 & | 3 \end{bmatrix} \\ &\sim r_{1} := r_{1} - r_{2}, \begin{bmatrix} 1 & 0 & 0 & | -1 \\ 0 & 1 & 0 & | 2 \\ 0 & 0 & 1 & | 3 \end{bmatrix} \\ &\text{So } x_{1} = -1, x_{2} = 2, x_{3} = 3 \text{ and the least square solution of} \\ &Ax = y \text{ is } x = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix}. \end{aligned}$$

5. Find the equation y = a + mx of the least square line that best fits the given data points. (0, 1), (1, 1), (3, 2).
Solution: We try to solve the equations 1 = a, 1 = a + m, 2 = a + 3m, that is, a = 1, a + m = 1 and a + 3m = 2. It corresponding to the linear system

$$a = 1, a + m = 1 \text{ and } a + 3m = 2.$$
 It corresponding to the linear 
$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} a \\ m \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$
  
Let  $A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \end{bmatrix}$ . We solve the normal equation

$$A^{T}A\begin{bmatrix} a\\ m \end{bmatrix} = A^{T}\begin{bmatrix} 1\\ 1\\ 2 \end{bmatrix}.$$
Compute  $A^{T}A = \begin{bmatrix} 1 & 1 & 1\\ 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0\\ 1 & 1\\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 4\\ 4 & 10 \end{bmatrix}$  and
$$A^{T}\begin{bmatrix} 1\\ 1\\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1\\ 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} 1\\ 1\\ 2 \end{bmatrix} = \begin{bmatrix} 4\\ 7 \end{bmatrix}.$$
Consider the augmented matrix
$$\begin{bmatrix} 3 & 4 & | & 4\\ 4 & 10 & | & 7 \end{bmatrix} \sim r_{2} := r_{2} - \frac{4}{3}r_{1}\begin{bmatrix} 3 & 4 & | & 4\\ 0 & \frac{14}{3} & | & \frac{5}{3} \end{bmatrix}$$

$$\sim r_{2} := \frac{3}{14}r_{2}\begin{bmatrix} 3 & 4 & | & 4\\ 0 & 1 & | & \frac{5}{14} \end{bmatrix} \sim r_{1} := r_{1} - 4r_{2}\begin{bmatrix} 3 & 0 & | & \frac{18}{7}\\ 0 & 1 & | & \frac{5}{14} \end{bmatrix}$$
So the last group colution is a -  $\frac{6}{7}$  and  $m = \frac{5}{7}$ . The

So the least square solution is  $a = \frac{6}{7}$  and  $m = \frac{5}{14}$ . The equation  $y = \frac{6}{7} + \frac{5}{14}x$  is the least square line that best fits the given data points. (0, 1), (1, 1), (3, 2).

6. (a) Show that the set of vectors

$$B = \left\{ u_1 = \left( -\frac{3}{5}, \frac{4}{5}, 0 \right), \ u_2 = \left( \frac{4}{5}, \frac{3}{5}, 0 \right), \ u_3 = (0, 0, 1) \right\}$$

is an **orthonormal basis** of  $\mathbb{R}^3$ .

Solution: Compute  $u_1 \cdot u_2 = \left(-\frac{3}{5}, \frac{4}{5}, 0\right) \cdot \left(\frac{4}{5}, \frac{3}{5}, 0\right) = \frac{-12}{5} + \frac{12}{5} = 0,$   $u_1 \cdot u_3 = \left(-\frac{3}{5}, \frac{4}{5}, 0\right) \cdot (0, 0, 1) = 0, u_2 \cdot u_3 = \left(\frac{4}{5}, \frac{3}{5}, 0\right) \cdot (0, 0, 1) = 0,$   $u_1 \cdot u_1 = \left(-\frac{3}{5}, \frac{4}{5}, 0\right) \cdot \left(-\frac{3}{5}, \frac{4}{5}, 0\right) = \frac{9}{25} + \frac{16}{25} = 1, u_3 \cdot u_3 = (0, 0, 1) \cdot (0, 0, 1) = 1,$  $u_2 \cdot u_2 = \left(\frac{4}{5}, \frac{3}{5}, 0\right) \cdot \left(\frac{4}{5}, \frac{3}{5}, 0\right) = \frac{16}{25} + \frac{9}{25} = 1$ 

(b) Find the coordinates of the vector (1, -1, 2) with respect to the basis in (a).

Solution: Let y = (1, -1, 2). So  $y = \frac{y \cdot u_1}{u_1 \cdot u_1} u_1 + \frac{y \cdot u_2}{u_2 \cdot u_2} u_2 + \frac{y \cdot u_3}{u_3 \cdot u_3} u_3 = (y \cdot u_1) u_1 + (y \cdot u_2) u_2 + (y \cdot u_3) u_3$ . Compute  $y \cdot u_1 = (1, -1, 2) \cdot \left(-\frac{3}{5}, \frac{4}{5}, 0\right) =$ 

$$\begin{array}{l} -\frac{3}{5} - \frac{4}{5} = -\frac{7}{5}, \ y \cdot u_2 = (1, -1, 2) \cdot \left(\frac{4}{5}, \frac{3}{5}, 0\right) = \frac{4}{5} - \frac{3}{5} = \frac{1}{5}, y \cdot u_3 = (1, -1, 2) \cdot (0, 0, 1) = 2. \end{array}$$

So the coordinate of y with respect to the basis in (a) is  $\left(-\frac{7}{5}, \frac{1}{5}, 2\right)$ .

7. (a) Let  $A = \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 2 & 3 & 4 \end{bmatrix}$ . Find the inverse matrix of A if possible.

Solution: Consider the augmented matrix  $[A I] = \begin{bmatrix} 3 & 6 & 7 & | & 1 & 0 & 0 \\ 0 & 2 & 1 & | & 0 & 1 & 0 \\ 2 & 3 & 4 & | & 0 & 0 & 1 \end{bmatrix}$  $\widetilde{r_{1} := r_{1} - r_{3}} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 2 & 1 & | & 0 & 1 & 0 \\ 2 & 3 & 4 & | & 0 & 0 & 1 \end{bmatrix}$   $\widetilde{r_{3} := r_{3} - 2r_{1}} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 2 & 1 & | & 0 & 1 & 0 \\ 0 & -3 & -2 & | & -2 & 0 & 3 \end{bmatrix}$ 
$$\begin{split} & \overbrace{r_2 := r_2 + r_3} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & -1 & -1 & | & -2 & 1 & 3 \\ 0 & -3 & -2 & | & -2 & 0 & 3 \end{bmatrix} \overbrace{r_2 := -r_2} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & -3 & -2 & | & -2 & 0 & 3 \end{bmatrix} \\ & \overbrace{r_3 := r_3 + 3r_2} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_4 := r_4 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & | & 2 & -1 & -3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix} \\ & \overbrace{r_5 := r_5 + 3r_5} \begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & -1 &$$
 $r_{2} := r_{2} - \widetilde{r_{3}, r_{1}} := r_{1} - 3r_{3} \begin{bmatrix} 1 & 3 & 0 & | & -11 & 9 & 17 \\ 0 & 1 & 0 & | & -2 & 2 & 3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix}$   $r_{1} := \widetilde{r_{1} - 3r_{2}} \begin{bmatrix} 1 & 0 & 0 & | & -5 & 3 & 8 \\ 0 & 1 & 0 & | & -2 & 2 & 3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix}.$ 

$$3r_2 \begin{bmatrix} 0 & 1 & 0 & | & -2 & 2 & 3 \\ 0 & 0 & 1 & | & 4 & -3 & -6 \end{bmatrix}$$

So  $A^{-1} = \begin{bmatrix} -5 & 3 & 8 \\ -2 & 2 & 3 \\ 4 & -3 & -6 \end{bmatrix}$ .

(b) Find the coordinates of the vector (1, -1, 2) with respect to the basis *B* obtained from the column vectors of *A*. Solution: The coordinate is  $x = A^{-1} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -5 & 3 & 8 \\ -2 & 2 & 3 \\ 4 & -3 & -6 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 8 \\ 2 \end{bmatrix}$ .

$$\begin{bmatrix} 2\\ -5 \end{bmatrix}$$
.

8. Let  $H = \left\{ \begin{bmatrix} a+2b-c\\a-b-4c\\a+b-2c \end{bmatrix} : a, b, cany real numbers \right\}.$ a. Explain why H is a subspace of  $R^3$ .  $\begin{bmatrix} a+2b-c \end{bmatrix} \begin{bmatrix} 1 \end{bmatrix} \begin{bmatrix} 2 \end{bmatrix} \begin{bmatrix} -1 \end{bmatrix}$ 

Solution: 
$$\begin{bmatrix} a + 2b & c \\ a - b - 4c \\ a + b - 2c \end{bmatrix} = a \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} + c \begin{bmatrix} -4 \\ -2 \end{bmatrix}$$
  
So  $H = Span\{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -4 \\ -2 \end{bmatrix}\}$  and  $H$  is a subspace.  
b. Find a set of vectors that spans  $H$ .  
$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} \begin{bmatrix} -1 \end{bmatrix}$$

Solution:  $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -4 \\ -2 \end{bmatrix} \right\}$  spans the space H. c. Find a basis for H.

Solution: Consider the matrix 
$$A = \begin{bmatrix} 1 & 2 & -1 \\ 1 & -1 & -4 \\ 1 & 1 & -2 \end{bmatrix}$$
  
 $r_2 := r_2 - \widetilde{r_1, r_3} := r_3 - r_1 \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & -3 \\ 0 & -1 & -1 \end{bmatrix}$ 

$$\widetilde{r_2} := \widetilde{r_2/(-3)} \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 1 \\ 0 & -1 & -1 \end{bmatrix} \widetilde{r_3} := \widetilde{r_3} + r_2 \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$
  
So the first two vectors are pivot vectors and  $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \right\}$  is a basis.  
The dimension of the subspace is 2.

d. What is the dimension of the subspace? Solution: The dimension of the subspace is 2. e. Find an orthogonal basis for H.

Solution: Let 
$$u_1 = \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$$
 and  $u_2 = \begin{bmatrix} 2\\-1\\1 \end{bmatrix}$ 

Then  $v_1 = u_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$  and  $v_2 = u_2 - \frac{u_2 \cdot v_1}{v_1 \cdot v_1} v_1$ . Compute  $u_2 \cdot v_1 = u_2 \cdot v_1$  $\begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 2 - 1 + 1 = 2 \text{ and } v_1 \cdot v_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 1 + 1 + 1 = 3.$  $v_{2} = \begin{bmatrix} 2\\ -1\\ 1 \end{bmatrix} - \frac{2}{3} \begin{bmatrix} 1\\ 1\\ 1 \end{bmatrix} = \begin{bmatrix} \frac{4}{3}\\ -\frac{5}{3}\\ \frac{1}{3} \end{bmatrix}. \text{ Thus } \{v_{1} = \begin{bmatrix} 1\\ 1\\ 1\\ 1 \end{bmatrix}, v_{2} = \begin{bmatrix} \frac{4}{3}\\ -\frac{5}{3}\\ \frac{1}{3} \end{bmatrix}\} \text{ ia an}$ orthogonal basis for H. We can verify that  $v_1 \cdot v_2 = 0$ .

9. Determine if the following systems are consistent and if so give all solutions in parametric vector form. (a)

Solution: The augmented matrix is  $\begin{bmatrix} 1 & -2 & 3 \\ 2 & -7 & 0 \\ -5 & 8 & 5 \end{bmatrix} \sim (r_2 := r_2 - 2r_1)$ 

$$\begin{bmatrix} 1 & -2 & 3 \\ 0 & -3 & -6 \\ -5 & 8 & 5 \end{bmatrix} \sim (r_3 := r_3 + 5r_1) \begin{bmatrix} 1 & -2 & 3 \\ 0 & -3 & -6 \\ 0 & -2 & 20 \end{bmatrix}$$

$$\sim (r_2 := r_2/-3, r_3 := r_3/-2) \begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & 2 \\ 0 & 1 & -10 \end{bmatrix} \sim (r_3 := r_3 - 2)$$

$$\begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & -12 \end{bmatrix}$$
The last row implies that  $0 = -12$  which is impossible. So this system is inconsistent.  
(b)
$$\begin{array}{c} x_1 & +2x_2 & -3x_3 & +x_4 = 1 \\ -x_1 & -2x_2 & +4x_3 & -x_4 = 6 \\ -2x_1 & -4x_2 & +7x_3 & -x_4 = 1 \end{bmatrix}$$
The augmented matrix is
$$\begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ -1 & -2 & 4 & -1 & 6 \\ -2 & -4 & 7 & -1 & 1 \end{bmatrix} \sim (r_2 := r_2 + r_1)$$

$$\begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ 0 & 0 & 1 & 0 & 7 \\ -2 & -4 & 7 & -1 & 1 \end{bmatrix} \sim (r_3 := r_3 + 2r_1) \begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 1 & 1 & 3 \end{bmatrix}$$

$$\sim (r_1 := r_1 - r_3) \begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 1 & -4 \end{bmatrix} \sim (r_1 := r_1 - r_3) \begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & 0 & 7 \\ 0 & 0 & 1 & -4 \end{bmatrix}$$

$$\sim (r_1 := r_1 - r_3) \begin{bmatrix} 1 & 2 & -3 & 1 & 1 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 1 & -4 \end{bmatrix} \sim (r_1 := r_1 + 3r_2) \begin{bmatrix} 1 & 2 & 0 & 0 & 26 \\ 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 0 & 1 & -4 \end{bmatrix}$$
So  $x_2$  is free. The solution is  $x_1 = 26 - 2x_2$ ,  $x_3 = 7$ ,  $x_4 = -47$ . Its

$$\begin{aligned} \text{parametric vector form is} \begin{bmatrix} x_1 \\ x_2 \\ x_4 \\ x_4 \end{bmatrix} = \begin{bmatrix} 26 - 2x_2 \\ 7 \\ -4 \end{bmatrix} = \begin{bmatrix} 26 \\ 0 \\ 7 \\ -4 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}. \end{aligned}$$
10. Let  $A = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 \\ 2 & -6 & 9 & -1 & 8 \\ 2 & -6 & 9 & -1 & 9 \\ -1 & 3 & -4 & 2 & -5 \end{bmatrix}$  which is row reduced to  $\begin{bmatrix} 1 & -3 & -2 & -20 & -3 \\ 0 & 0 & 1 & 3 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$   
(a) Find a basis for the column space of  $A$   
(b) Find a basis for the nullspace of  $A$   
(c) Find the rank of the matrix  $A$   
(d) Find the dimension of the nullspace of  $A$ .  
(e) Is  $\begin{bmatrix} 1 \\ 4 \\ 1 \\ 1 \end{bmatrix}$  in the range of  $A$ ?  
(e) Does  $Ax = \begin{bmatrix} 0 \\ 3 \\ 2 \\ 0 \end{bmatrix}$  have any solution? Find a solution if it's solvable.  
Solution: Consider the augmented matrix  $\begin{bmatrix} 1 & -3 & 4 & -2 & 5 & | & 1 & | & 0 \\ 2 & -6 & 9 & -1 & 8 & | & 4 & | & 3 \\ 2 & -6 & 9 & -1 & 9 & | & 3 & | & 2 \\ -1 & 3 & -4 & 2 & -5 & | & 1 & | & 0 \end{bmatrix}$   
 $-2r_1 + r_2, -2r_1 + r_3, r_1 + r_4 \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & | & 1 & | & 0 \\ 0 & 0 & 1 & 3 & -2 & | & 2 & | & 3 \\ 0 & 0 & 1 & 3 & -1 & | & 1 & | & 2 \\ 0 & 0 & 1 & 3 & -1 & | & 1 & | & 2 \\ 0 & 0 & 1 & 3 & -1 & | & 1 & | & 2 \\ 0 & 0 & 0 & 0 & 0 & | & 2 & | & 0 \end{bmatrix}$ 

So the first, third and fifth vector forms a basis for Col(A), i.e  $\left\{ \begin{bmatrix} 1 \\ 2 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 4 \\ 9 \\ 9 \\ -4 \end{bmatrix}, \begin{bmatrix} 5 \\ 8 \\ 9 \\ -5 \end{bmatrix} \right\}$ 

is a basis for Col(A). The rank of A is 3 and the dimension of the null space is 5-3=2.

$$x \in Null(A) \text{ if } x_1 - 3x_2 - 14x_4 = 0, \ x_3 + 3x_4 = 0 \text{ and } x_5 = 0. \text{ So}$$

$$x = \begin{bmatrix} 3x_2 + 14x_4 \\ x_2 \\ -x_4 \\ x_4 \\ 0 \end{bmatrix} = x_2 \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 14 \\ 0 \\ -1 \\ 1 \\ 0 \end{bmatrix}. \text{ Thus} \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 14 \\ 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} \text{ is a basis}$$
for  $NULL(A).$ 

$$\begin{bmatrix} 1 \end{bmatrix}$$

From the result of row reduction, we can see that  $Ax = \begin{bmatrix} 1\\4\\3\\1 \end{bmatrix}$  is incon-

sistent (not solvable) and 
$$\begin{bmatrix} 1\\4\\3\\1 \end{bmatrix}$$
 is not in the range of  $A$ .  
From the result of row reduction, we can see that  $Ax = \begin{bmatrix} 0\\3\\2\\0 \end{bmatrix}$  is solvable.

11. Determine if the columns of the matrix form a linearly independent set. Justify your answer.

$$\begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}, \begin{bmatrix} 1 & -2 \\ -2 & 4 \\ 3 & 6 \end{bmatrix}, \begin{bmatrix} -4 & -3 & 0 \\ 0 & -1 & 4 \\ 1 & 0 & 3 \\ 5 & 4 & 6 \end{bmatrix}, \begin{bmatrix} -4 & -3 & 1 & 5 & 1 \\ 2 & -1 & 4 & -1 & 2 \\ 1 & 2 & 3 & 6 & -3 \\ 5 & 4 & 6 & -3 & 2 \end{bmatrix}.$$

Solution:  $det \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = 2 - 1 = 1 \neq 0$ . So the columns of the matrix form a linearly independent set.

 $\begin{bmatrix} 1 & -2 \\ -2 & 4 \\ 3 & 6 \end{bmatrix}$ . The second column vector is a multiple of the first column vector. So the columns of the matrix form a linearly dependent set.

$$\begin{bmatrix} -4 & -3 & 0 \\ 0 & -1 & 4 \\ 1 & 0 & 3 \\ 5 & 4 & 6 \end{bmatrix} \quad interchange \ \widetilde{first} \ and \ third \ row \begin{bmatrix} 1 & 0 & 3 \\ 0 & -1 & 4 \\ -4 & -3 & 0 \\ 5 & 4 & 6 \end{bmatrix}$$

$$\widetilde{r_3 + 4r_1, r_4 + (-5)r_1} \begin{bmatrix} 1 & 0 & 3 \\ 0 & -1 & 4 \\ 0 & -3 & 12 \\ 0 & 4 & -9 \end{bmatrix} \qquad \widetilde{(-1)r_2} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -4 \\ 0 & -3 & 12 \\ 0 & 4 & -9 \end{bmatrix}$$

$$\widetilde{r_3 + 3r_2, r_4 + (-4)r_2} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -4 \\ 0 & 0 & 0 \\ 0 & 0 & 7 \end{bmatrix} \quad interchange \ 3rd \ and \ 4th \ row, \frac{1}{7}r_4 \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -4 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

This matrix has three pivot vectors. So the columns of the matrix form a linearly independent set.

The column vectors of

$\left\lceil -4 \right\rceil$	-3	1	5	1]
2	-1	4	-1	2
1	2	3	6	-3
5	4	6	-3	2

form a dependent set since we have five column vectors in  $\mathbb{R}^4$ .

12. Let A be a  $12 \times 5$  matrix. You may assume that  $Nul(A^TA) = Nul(A)$ . (This relation holds form any matrix A.)

a. What is the size of  $A^T A$ ?

b. Use the Rank Theorem to obtain an equation involving rankA. Find another equation involving  $rank(A^TA)$ . What is the connection between these two ranks?

c. Suppose the columns of A are linearly independent. Explain why  $A^T A$  is invertible.

Solution: a. Note that Nul(A) is the dimension of the null space of A. Since  $A^T$  is a  $5 \times 12$  matrix and A is a  $12 \times 5$ , we know that  $A^T A$  is a  $5 \times 5$  matrix.

b. rank(A) + Nul(A) = 5 and  $rank(A^TA) + Nul(A^TA) = 5$ . Using the fact that  $Nul(A^TA) = Nul(A)$ , we know that  $rank(A) = rank(A^TA)$ . c. The columns of A are linearly independent implies that rank(A) = 5. So  $rank(A^TA) = 5$ . Recall that  $A^TA$  is a  $5 \times 5$  matrix. This implies that  $A^TA$  is a invertible matrix.